

1.2 Instruction, exécution et résultat

```
[> 2 + 2;           4          (1.1)
=> 2 + 2           4          (1.2)
[=> 2 + 2 :        5          (1.3)
=> 2 + 3;
=> 4 · 5;
```

1.3 Opérations de bases

```
[>
[> sqrt(2 + 3·7 / 5);      1/5 * sqrt(155)    (2.1)
=> abs(1 - 2 · 5);         31                  (2.2)
[=> cos(Pi / 2);           0                  (2.3)
=> exp(1); ln(1);         e                  (2.4)
[=> evalf(exp(1));         2.718281828       (2.5)
[=> ?plot
=> exp(1);                 e                  (2.6)
=>
```

1.4 Les variables

```
[> Digits;
```

```

evalf(Pi);
          10
          3.141592654
(3.1)

> a;
          a
(3.2)

> a := 1; a;
          a := 1
          1
(3.3)

> a := 1;
unassign('a');
a;
          a := 1
          a
(3.4)

> Digits := 50;
evalf(Pi);
          Digits := 50
          3.1415926535897932384626433832795028841971693993751
(3.5)

> Digits = 20;
Digits;
          50 = 20
          50
(3.6)

> ?unassign
> Pi := 3.14;
Error, attempting to assign to `Pi` which is protected
> a := 10 : b := 43 :
a; b;
          10
          43
(3.7)

> restart;
> a; b;
          a
          b
(3.8)

> a := 167;
          a := 167
(3.9)

> a :=  $\frac{a}{10}$ ;
          a :=  $\frac{167}{100000}$ 
(3.10)

```

1.5 Boucles et instructions conditionnelles

1.5.1 Boucles

```
> montant := 0 :  
  for i from 1 to 32  
    do montant := montant + 10;  
  od:  
  montant;
```

320 (4.1.1)

```
> montant := 0 :  
  for i to 32  
    do montant := montant + 10;  
  od:  
  montant;
```

320 (4.1.2)

```
>
```

1.5.2 Tests if/while

```
> a := 10 : b := 0 :  
  if (a > 10) then  
    print(Coucou);  
  else b := evalf(sqrt(a));  
  fi:  
  a; b;
```

10
3.162277660 (4.2.1)

```
> n := 0 :  
  while (n·n < 1000)  
    do n := n + 1 :  
  od:  
  n;
```

32 (4.2.2)

```
> 32·32;
```

1024 (4.2.3)

```
> 31·31;
```

961 (4.2.4)

```
> n := 0 :  
  while (n·n < 1000)  
    do n := n + 1 :  
    print(n);  
  od:
```

n;

1

2

3

4

5

6

7

8

9

10

11

12

13

14

15

16

17

18

19

20

21

22

23

24

25

26

27

28

29

30

31

32

32

(4.2.5)

=>

▼ 1.5.3 Opérateurs logiques

```

> a := 11 : b := 5 : c := 0 :
  if ((a > 10) and (b = 7)) then
    c := 40 :
  fi:
  c;
0
(4.3.1)

> a := 11 : b := 5 : c := 0 :
  if ((a > 10) or (b = 7)) then
    c := 40 :
  fi:
  c;
40
(4.3.2)

> a := 10 :
  if (a ≥ 10) then
    print(Coucou) :
  fi:
  Coucou
Coucou
(4.3.3)

```

1.6 Les fonctions

1.6.1 Fonctions et expressions

```

> f:= x→x2 + 1;
f:= (x,y)→x2 + y + 1
(5.1.1)

> f(0.1, 0.5);
1.51
(5.1.2)

> f(0.5);
1.25
(5.1.3)

> restart;
> f:= x2 + 1;
f:= x2 + 1
(5.1.4)

> f(0.1);
x(0.1)2 + 1
(5.1.5)

> subs(x = 0.1,f);
1.01
(5.1.6)

> f:= (x,y)→x2 + y + 1;
f:= (x,y)→x2 + y + 1
(5.1.7)

```

```

> f(0.1, 0.5);                                1.51
>
> restart;
> f := x2 + y + 1;                         f:=x2 + y + 1      (5.1.9)
>                                                 x(0.1)2 + 1       (5.1.10)
> subs(x = 0.1, y = 0.5, f);                 1.51
>                                                 f:=x→x2 + 1      (5.1.11)
> f := x2 + 1 :                            f:=x→x2 + 1      (5.1.12)
> f := unapply(f, x);
> restart;
> f := x→x2 + 1 :                         f:=x2 + 1      (5.1.13)
> f := f(x);
>

```

1.6.2 Procédures

```

> toto := proc(f, N)
  local intrec, i;
  intrec := 0;
  for i from 1 to N
    do intrec := intrec + evalf(subs(x =  $\frac{i}{N}$ , f));
  od;
  intrec;
  end proc;
> f := x2 + 1 : N := 100 :
  toto(f, N); evalf( $\frac{4}{3}$ );
1.338350000
1.333333333
(5.2.1)

> f := x : N := 10000 :
  toto(f, N);
0.5000500000
(5.2.2)
>

```



1.7 Les tableaux

1.7.1 La commande array

```
> N := 100 : c := array(1..N);  
c := array(1..100, [ ]) (6.1.1)
```

```
> c[6] := 1;  
c6 := 1 (6.1.2)
```

```
> c[6];  
1 (6.1.3)
```

```
> c[5];  
c5 (6.1.4)
```

```
> deb := -10 : fin := 15 : c := array(deb..fin);  
c[-5];  
c := array(-10..15, [ ])  
c-5 (6.1.5)
```

```
> N := 100 :  
c := array(1..N) :  
c[1] := 1/7 :  
for k from 2 to N do  
T := add(c[j], j = 1..k-1) :  
S := add(j*c[j]*c[k-j], j = 1..k-1) :  
c[k] := 6/(5*k+9)*(S + 1/3 - T) :  
od:  
> evalf(c[100]);  
2.989229284 10-10 (6.1.6)
```

```
>  
>
```

1.7.2 Les listes

```
> L := [1, 4, 7];  
L := [1, 4, 7] (6.2.1)
```

```
> nops(L);  
3 (6.2.2)
```

```

> L := [3, 6, 7];
L := [3, 6, 7] (6.2.3)
> L[2];
6 (6.2.4)
> op(2, L);
6 (6.2.5)
> L := [ seq(i·i, i = 1 .. 5) ];
L := [1, 4, 9, 16, 25] (6.2.6)
> N := 10:
L :=  $\left[ \text{seq}\left(\frac{k}{N}, k = 1 .. N\right) \right];$ 
f := x → exp(x):
fL := map(f, L);
L :=  $\left[ \frac{1}{10}, \frac{1}{5}, \frac{3}{10}, \frac{2}{5}, \frac{1}{2}, \frac{3}{5}, \frac{7}{10}, \frac{4}{5}, \frac{9}{10}, 1 \right]$ 
fL :=  $\left[ e^{\frac{1}{10}}, e^{\frac{1}{5}}, e^{\frac{3}{10}}, e^{\frac{2}{5}}, e^{\frac{1}{2}}, e^{\frac{3}{5}}, e^{\frac{7}{10}}, e^{\frac{4}{5}}, e^{\frac{9}{10}}, e \right]$  (6.2.7)
>

```

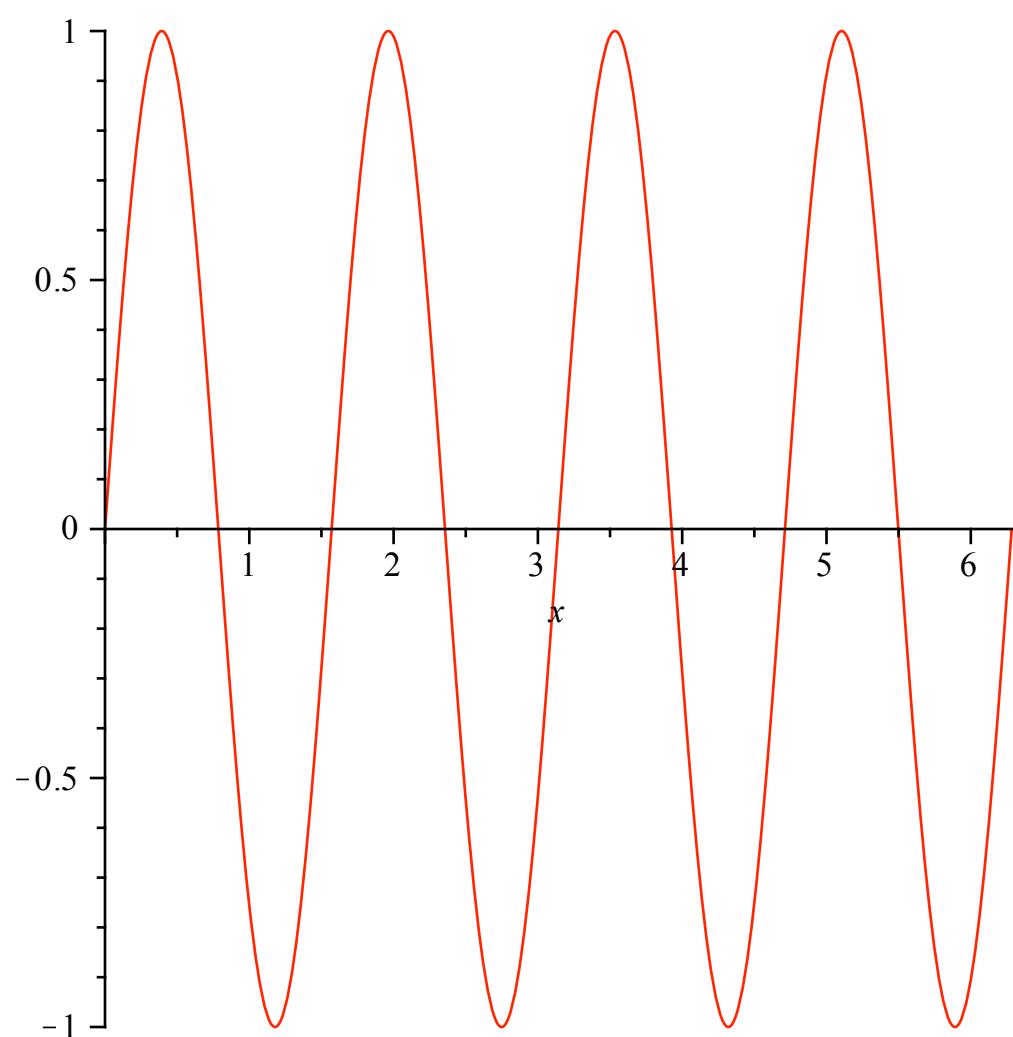
▼ 1.8 Graphiques

▼ 1.8.1 Des fonctions

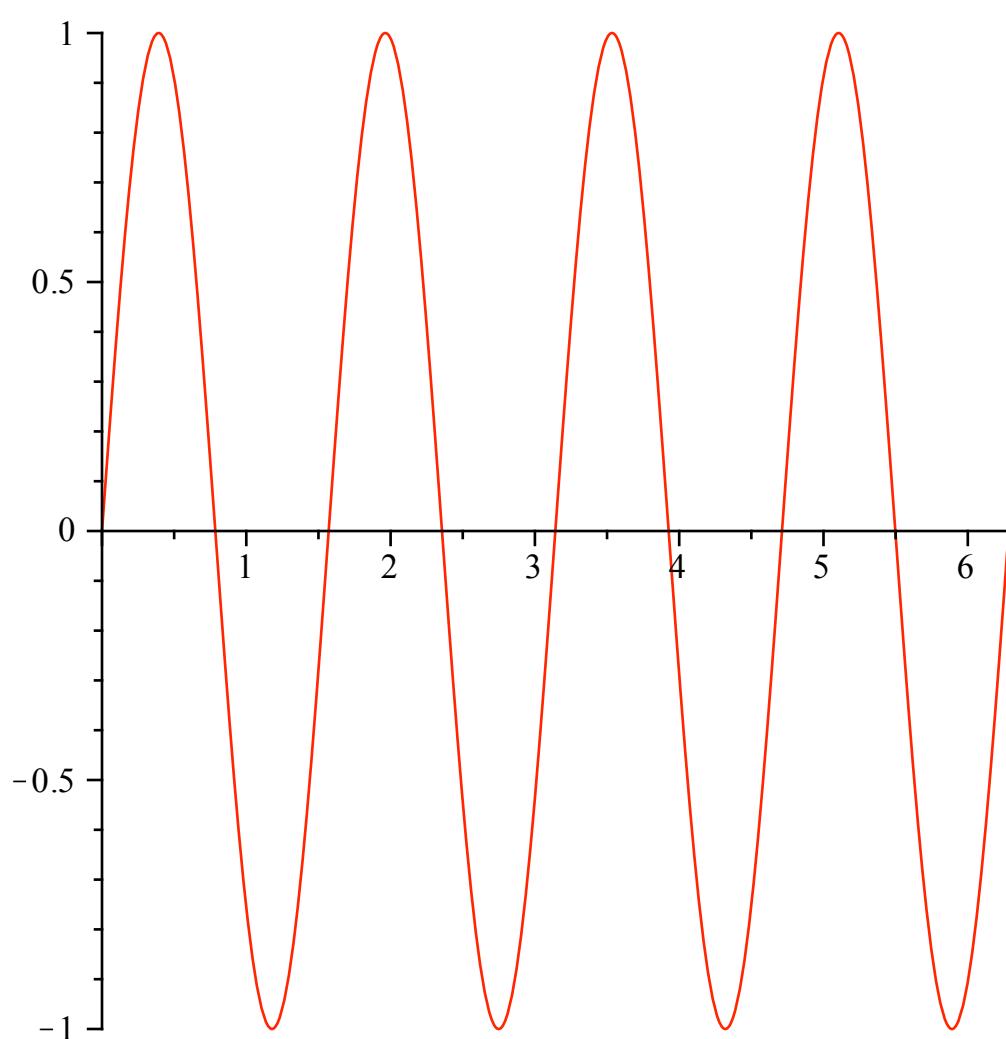
```

> f := sin(4·x):
plot(f, x = 0 .. 2·Pi);

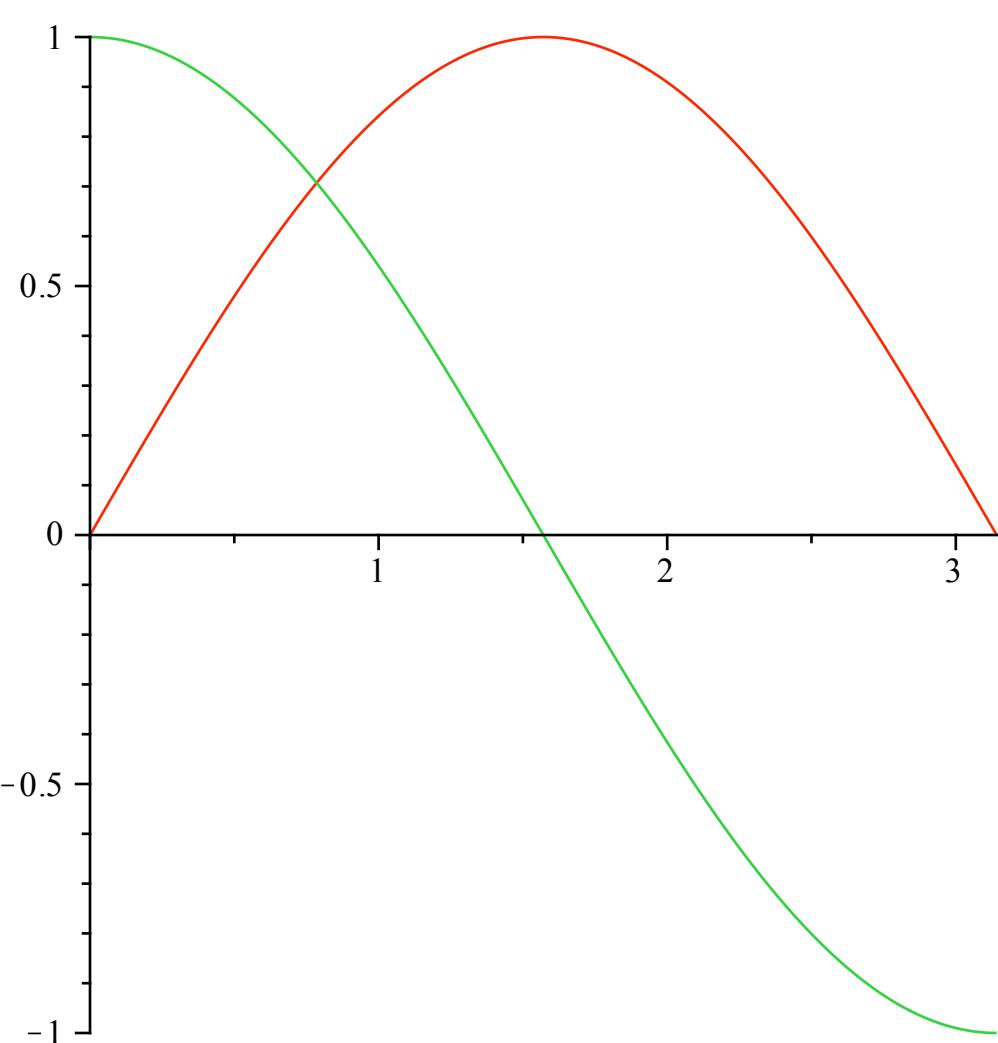
```



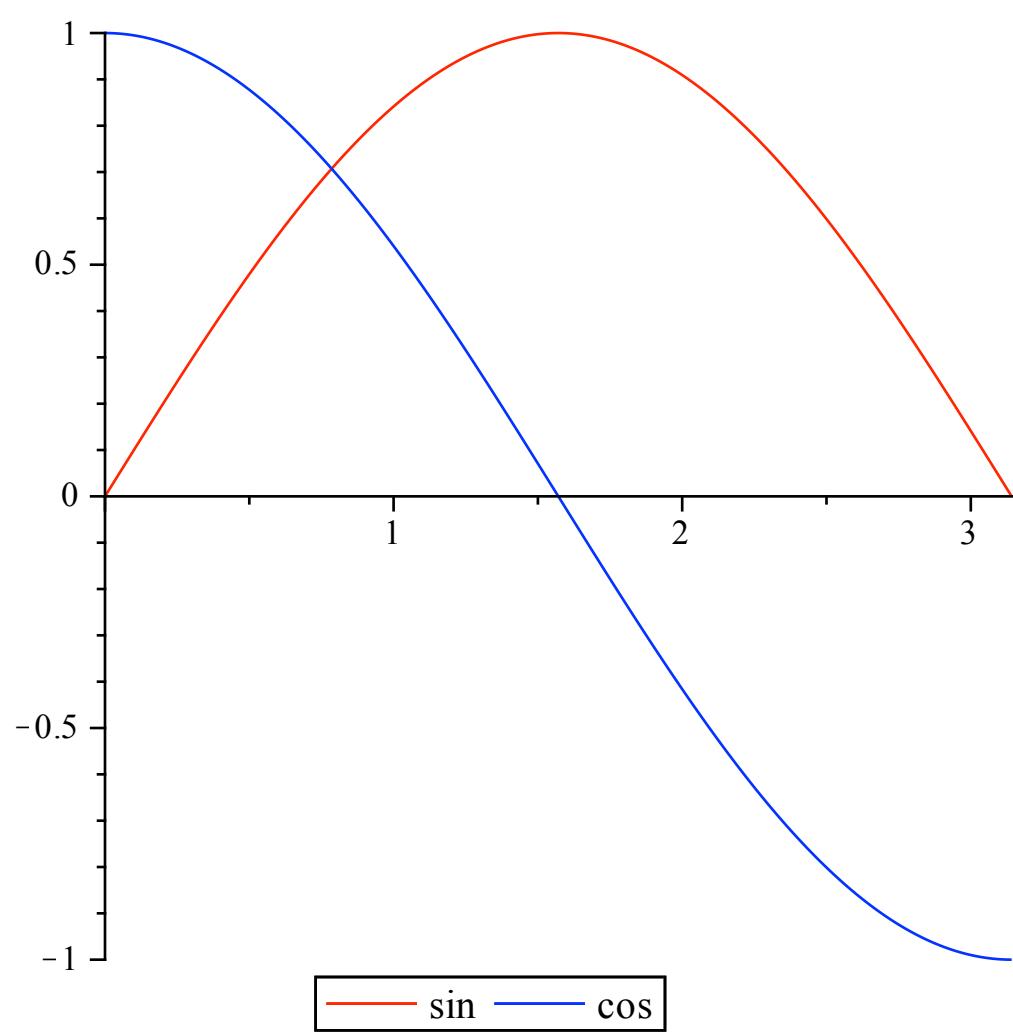
```
> f:= x->sin(4*x):  
plot(f, 0 .. 2*Pi);
```



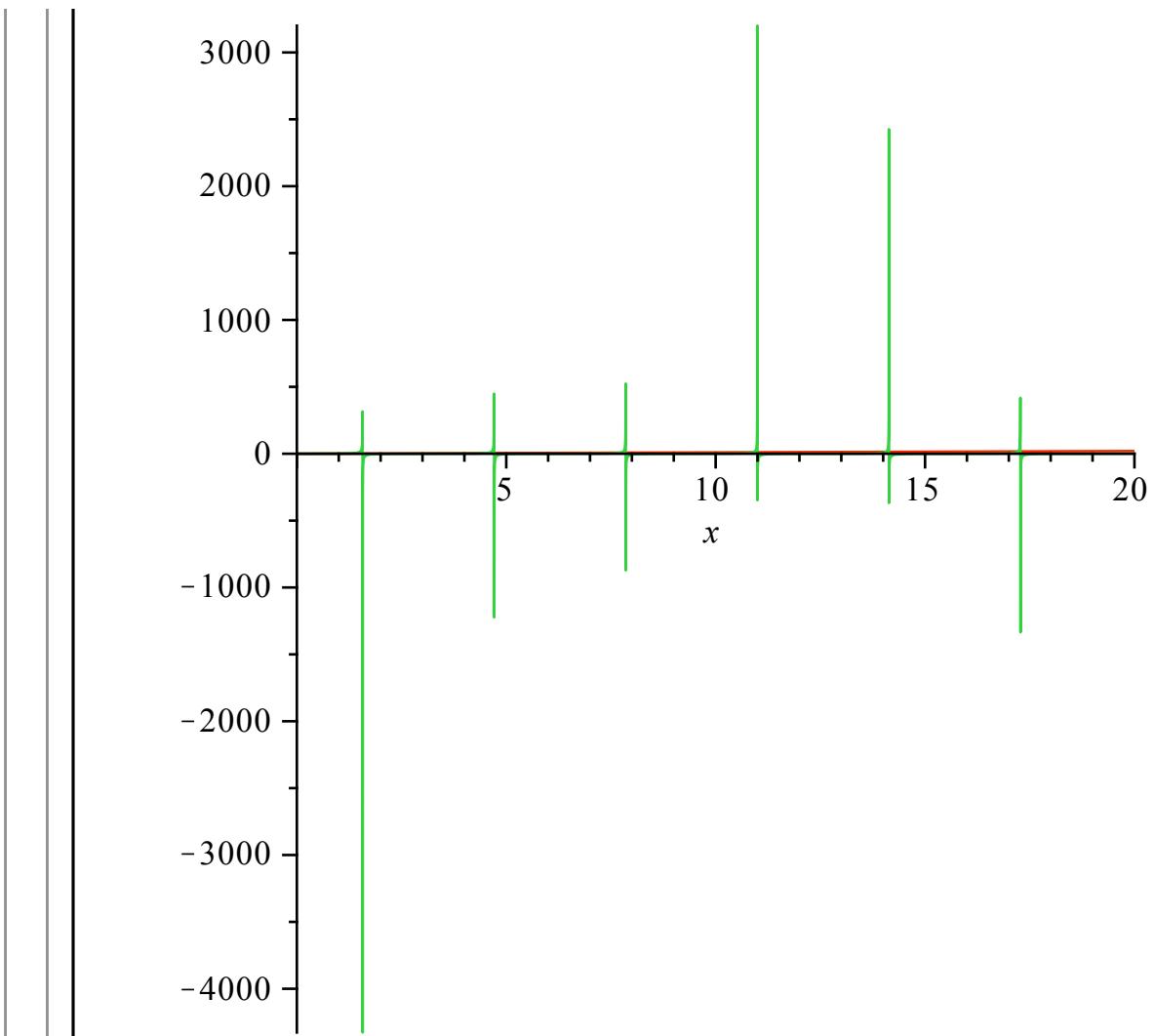
```
> plot([sin, cos], 0..Pi);
```



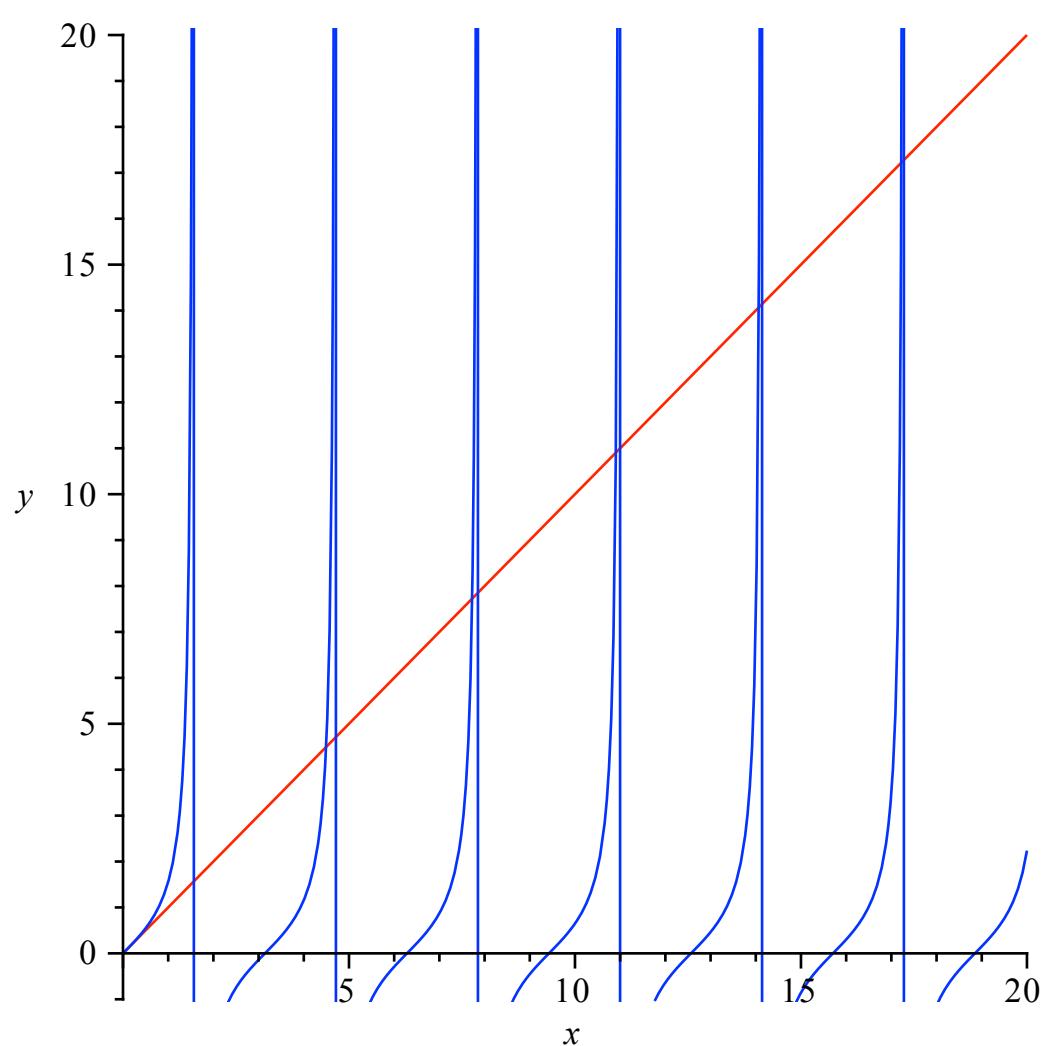
```
> plot([sin, cos], 0..Pi, color = [red, blue], legend = ["sin", "cos"]);
```



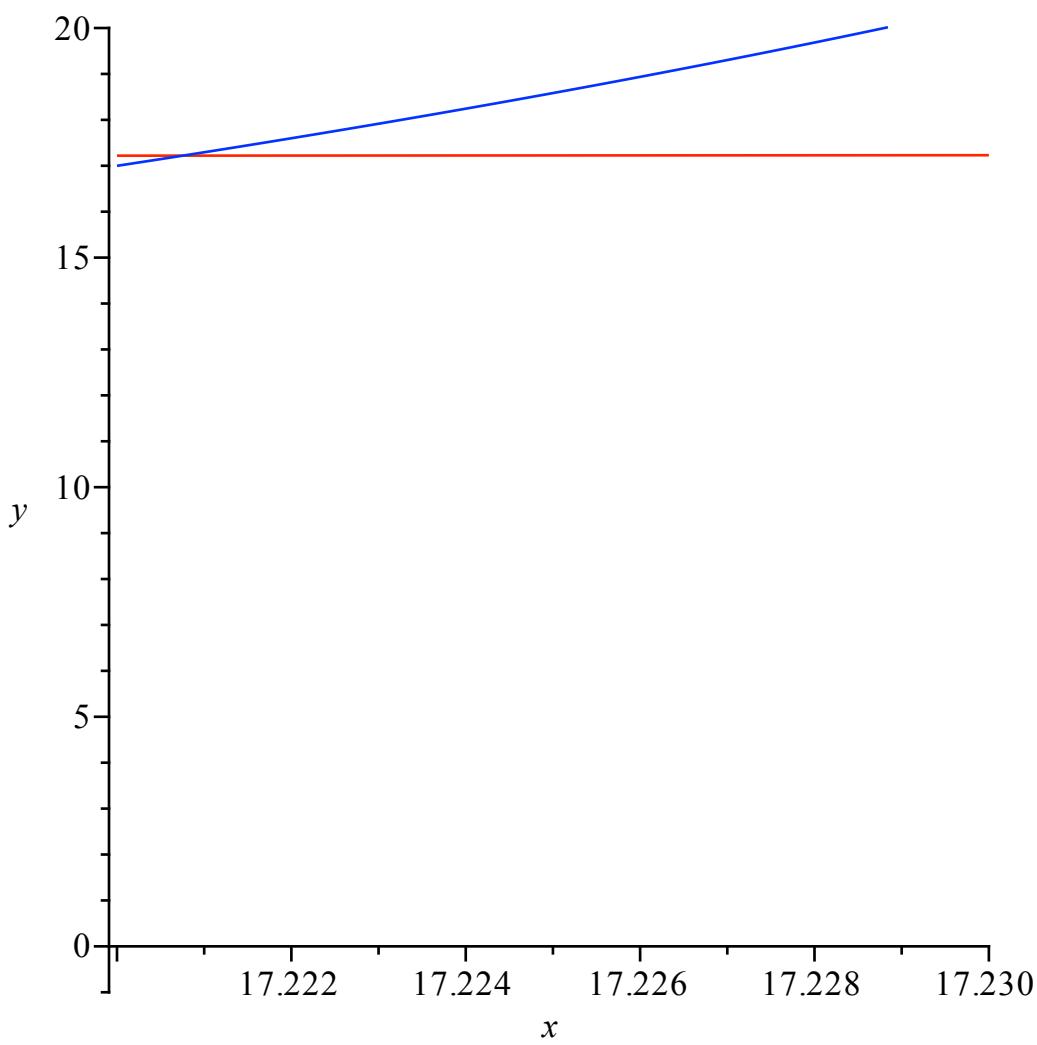
```
> ?plot3d  
> #Exercice  
> plot([x, tan(x)], x = 0 .. 20);
```



```
> plot([x, tan(x)], x=0..20, y=-1..20, color=[red, blue]);
```



```
> plot([x, tan(x)], x = 17.22..17.23, y = -1..20, color = [red, blue]);
```



```
> fsolve(x = tan(x), x = 17.22 .. 17.23); 17.22075527 (7.1.1)
```

```
> #Fin exercice
> with(plots);
[animate, animate3d, animatecurve, arrow, changecoords, complexplot, complexplot3d,
conformal, conformal3d, contourplot, contourplot3d, coordplot, coordplot3d,
densityplot, display, dualaxisplot, fieldplot, fieldplot3d, gradplot, gradplot3d,
implicitplot, implicitplot3d, inequal, interactive, interactiveparams, intersectplot,
listcontplot, listcontplot3d, listdensityplot, listplot, listplot3d, loglogplot, logplot,
matrixplot, multiple, odeplot, pareto, plotcompare, pointplot, pointplot3d, polarplot,
polygonplot, polygonplot3d, polyhedra_supported, polyhedraplot, rootlocus,
semilogplot, setcolors, setoptions, setoptions3d, spacecurve, sparsematrixplot,
surfdata, textplot, textplot3d, tubeplot] (7.1.2)
```

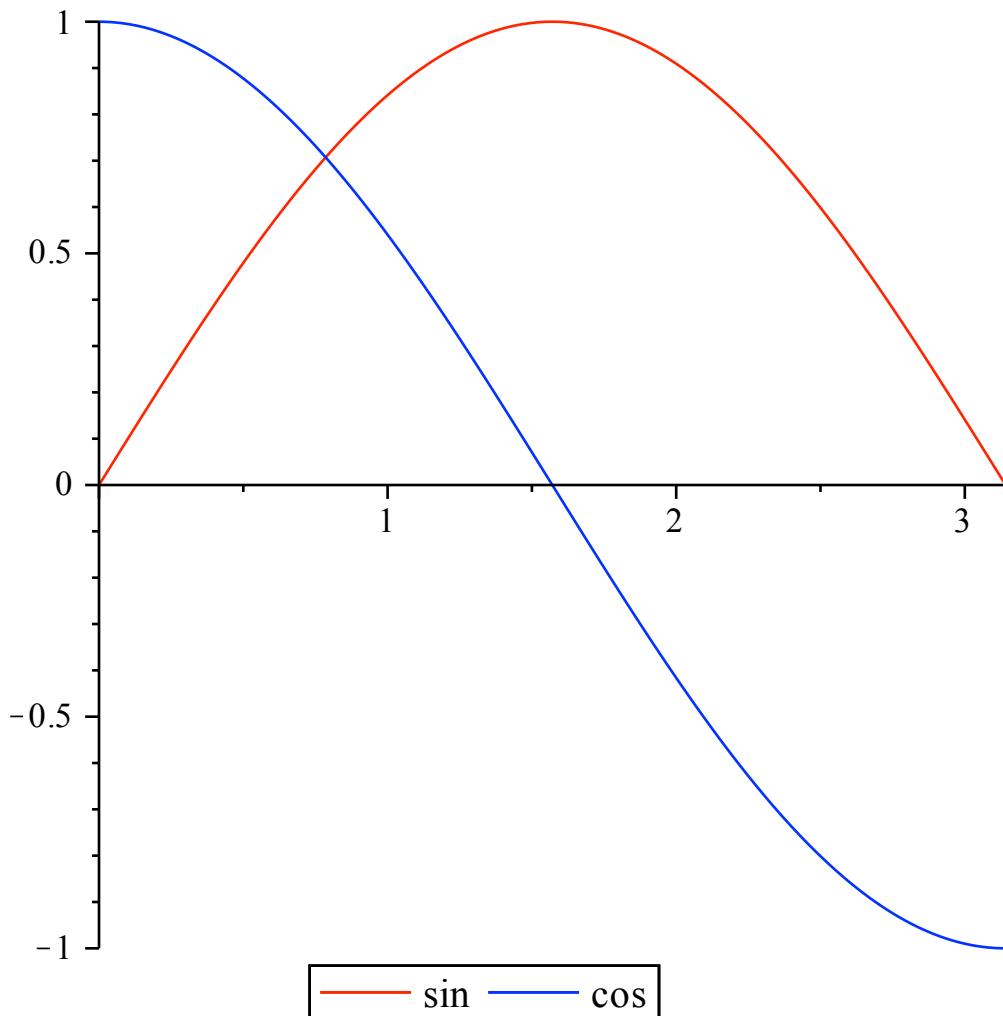
```
> G1 := plot(sin, 0 .. Pi, color = red, legend = "sin");
G2 := plot(cos, 0 .. Pi, color = blue, legend = "cos");
G1 := PLOT(...)
```

(7.1.3)

```
G2 := PLOT(...)
```

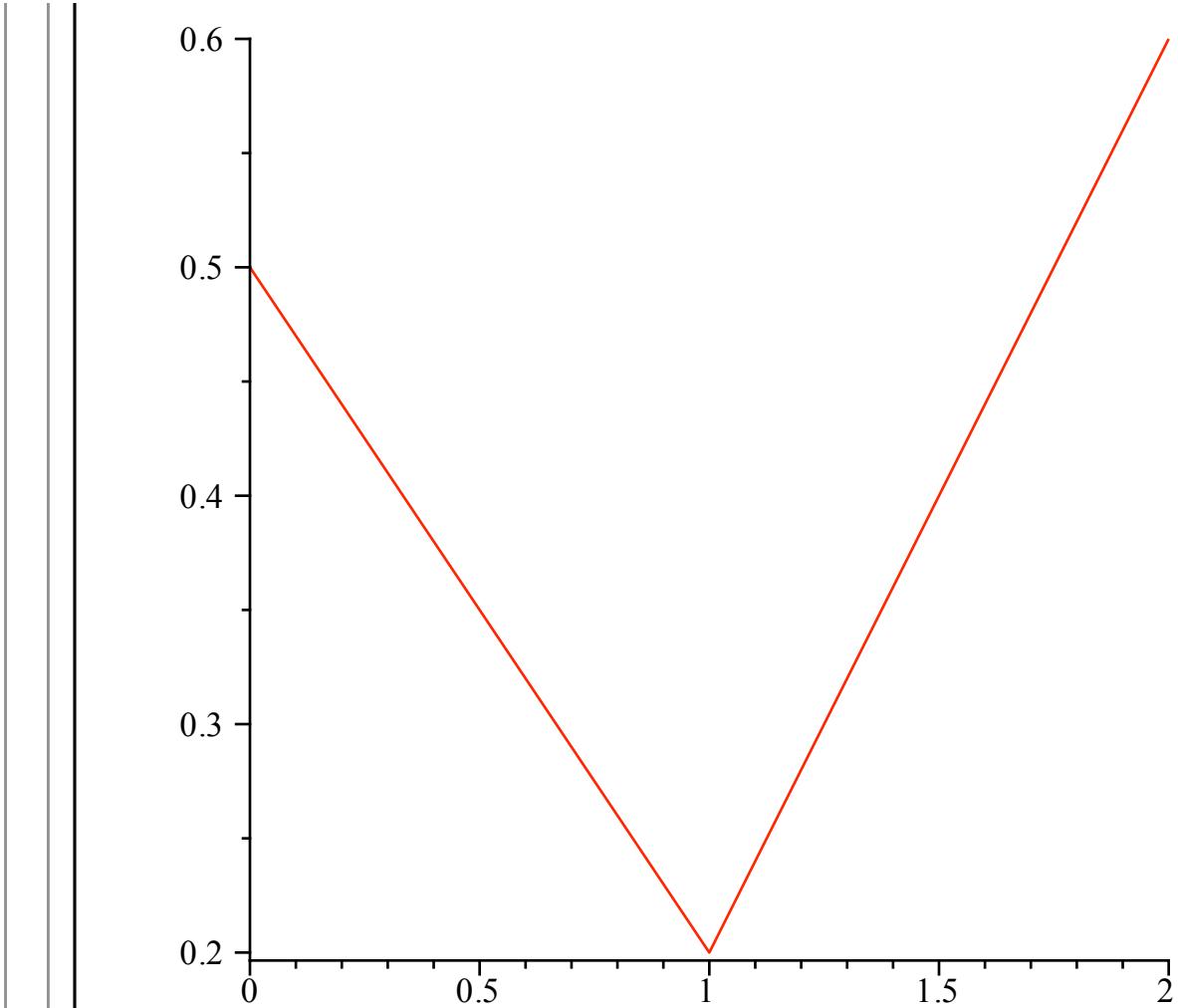
(7.1.3)

```
> display(G1, G2);
```

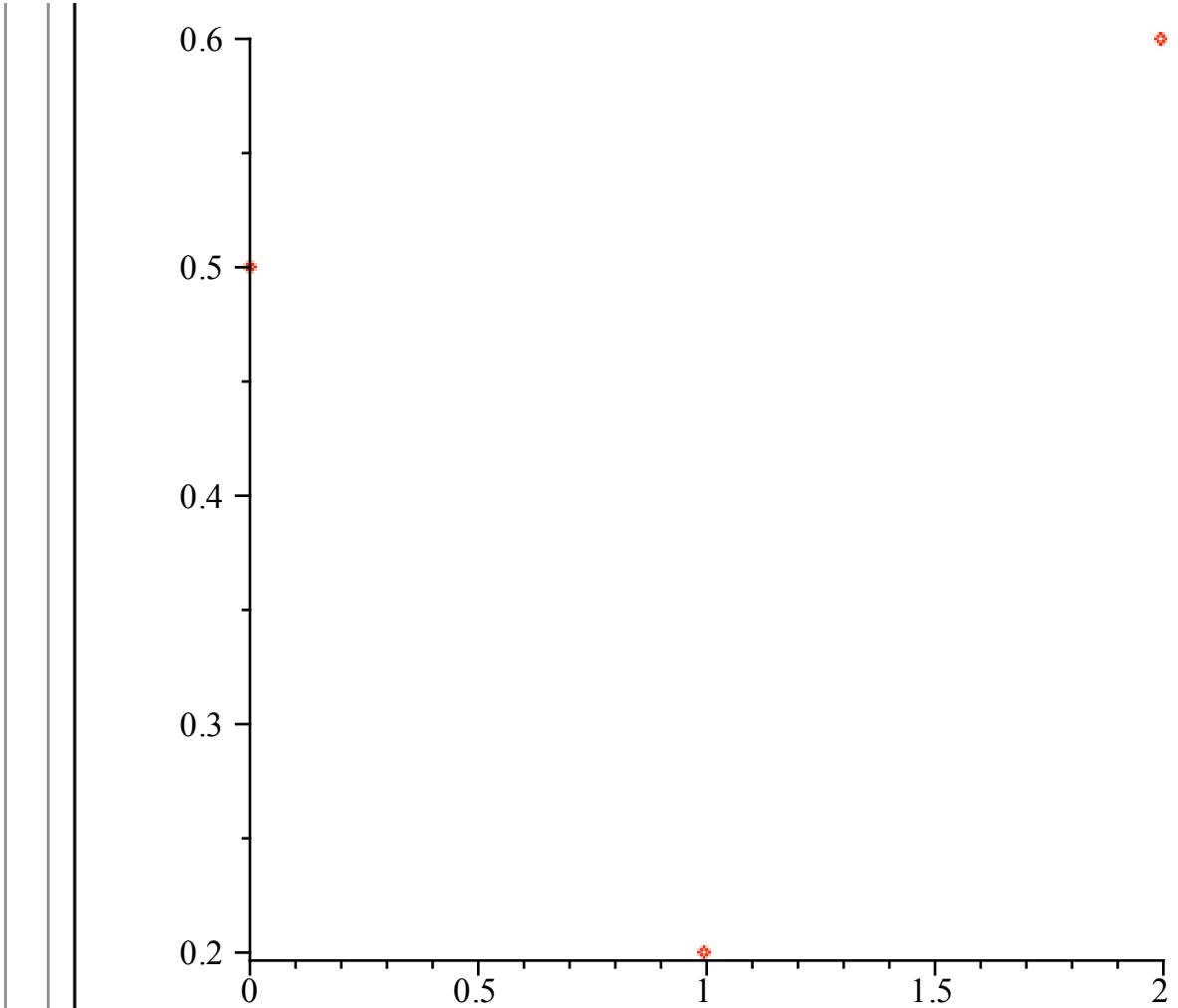


▼ 1.8.2 Un ensemble de points

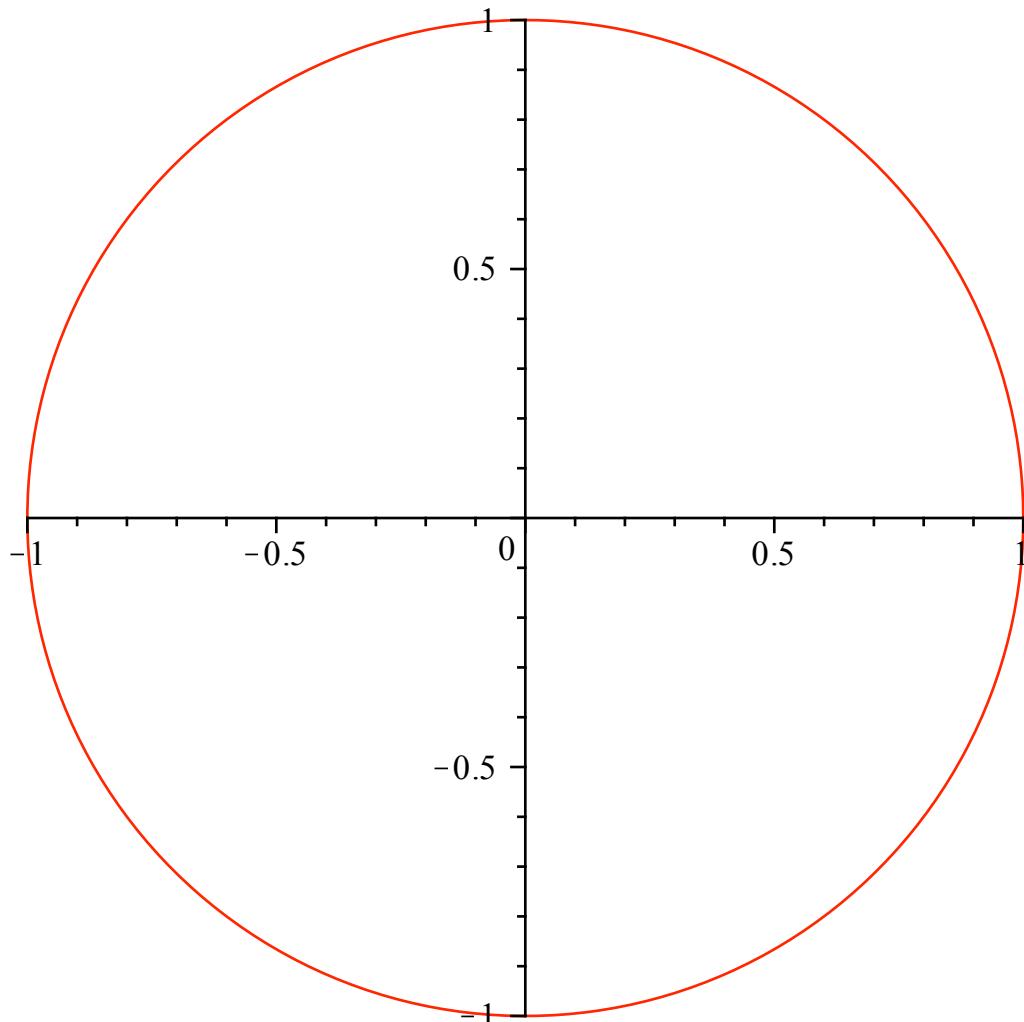
```
> plot([[0, 0.5], [1, 0.2], [2, 0.6]]);
```



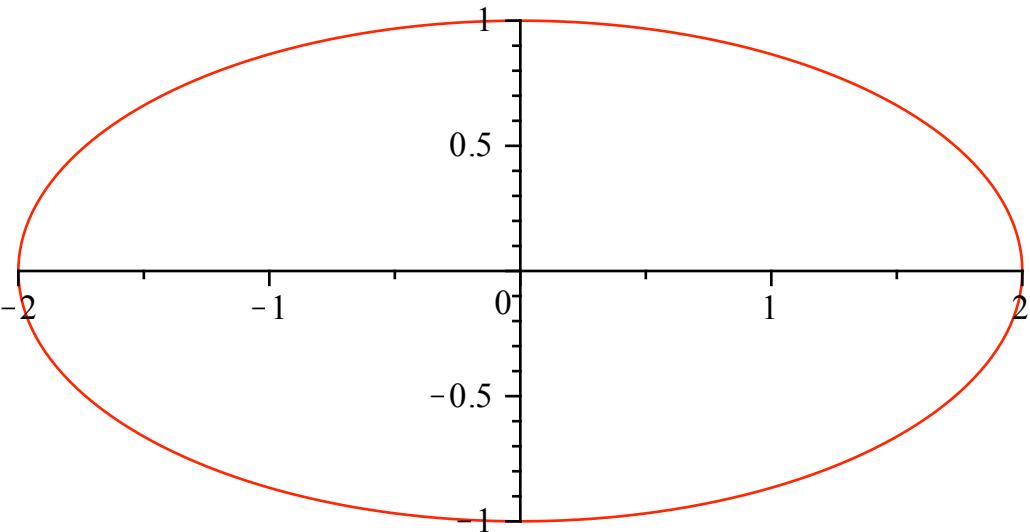
```
> plot([[0, 0.5], [1, 0.2], [2, 0.6]], style=point);
```



```
> plot([cos(t), sin(t), t = 0 .. 2·Pi], scaling = constrained);
```



```
> plot( [2· cos(t), sin(t), t= 0 .. 2·π], scaling = constrained);
```



1.9 Résolution d'équations différentielles

- > $f := x \rightarrow x^3;$
 $D(f);$
 - > $D(f)(0);$
 - > $diff(f(x), x);$
 - > $subs(x=0, diff(f(x), x));$
- (8.1)
- (8.2)
- (8.3)
- (8.4)

```

> f:=x3;
    diff(f,x);
          f:=x3
          3 x2                                (8.5)

> diff(f,x,x);
          6 x                                (8.6)

> diff(ln(x),x);
          1
          x                                (8.7)

> #ressort
> restart;
> m := 2; alpha := 0.5; k := 5;
          m := 2
          α := 0.5
          k := 5                                (8.8)

> ressort := {m·diff(x(t),t,t) + alpha·diff(x(t),t) + k·x(t) = 0};
          ressort := {2 · (d2 x(t) / dt2) + 0.5 · (d x(t) / dt) + 5 x(t) = 0}      (8.9)

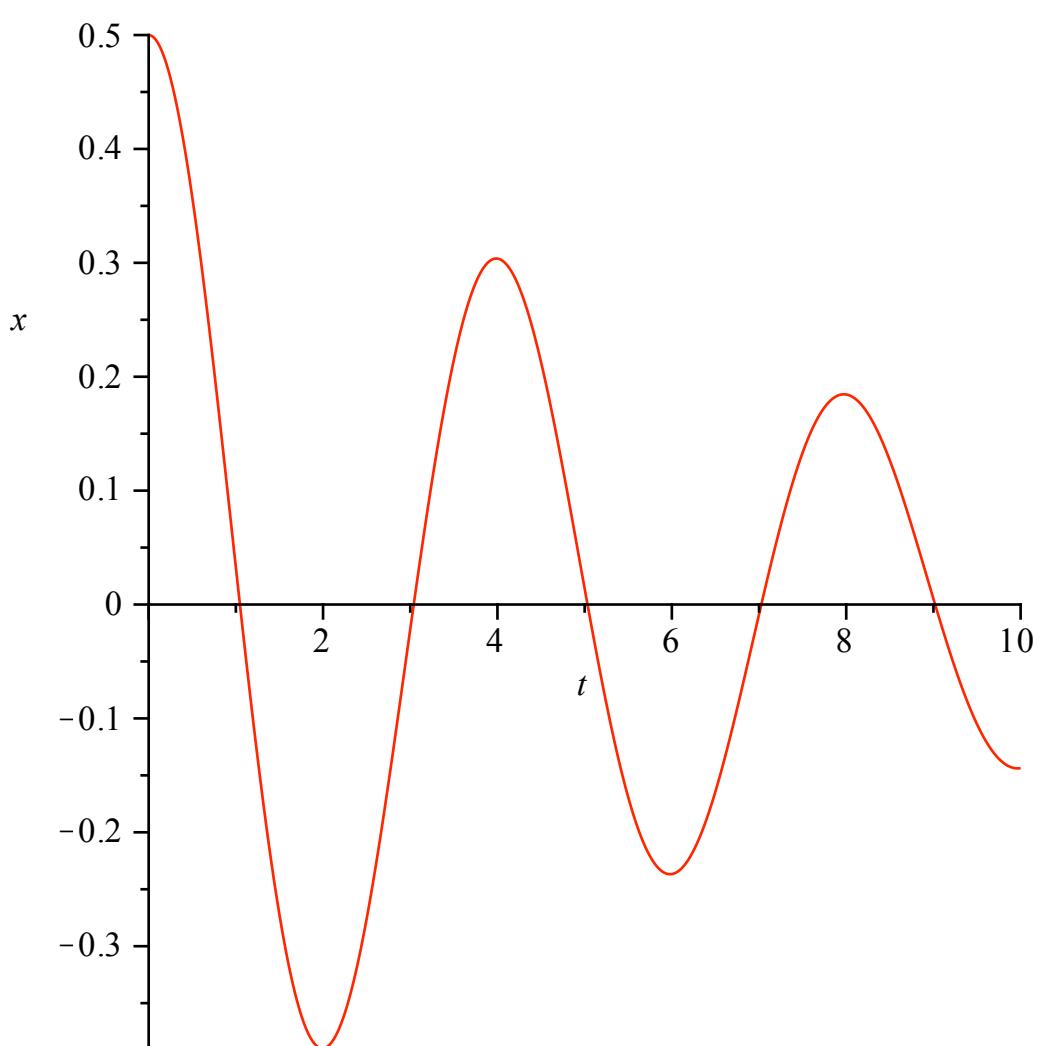
> CI := (a,b) → {x(0) = a, D(x)(0) = b};
          CI := (a,b) → {x(0) = a, D(x)(0) = b}                                (8.10)

> sol := dsolve(ressort union CI(0.5,0),x(t),numeric);
          sol := proc(x_rkf45) ... end proc                                (8.11)

> with(plots);
[animate, animate3d, animatecurve, arrow, changecoords, complexplot, complexplot3d,
conformal, conformal3d, contourplot, contourplot3d, coordplot, coordplot3d,
densityplot, display, dualaxisplot, fieldplot, fieldplot3d, gradplot, gradplot3d, implicitplot,
implicitplot3d, inequal, interactive, interactiveparams, intersectplot, listcontplot,
listcontplot3d, listdensityplot, listplot, listplot3d, loglogplot, logplot, matrixplot, multiple,
odeplot, pareto, plotcompare, pointplot, pointplot3d, polarplot, polygonplot,
polygonplot3d, polyhedra_supported, polyhedraplot, rootlocus, semilogplot, setcolors,
setoptions, setoptions3d, spacecurve, sparsematrixplot, surfdata, textplot, textplot3d,
tubeplot]                                (8.12)

> odeplot(sol, [t,x(t)], 0 .. 10, numpoints = 400);

```



```
> odeplot(sol, [x(t), diff(x(t), t)], 0..10, numpoints = 400);
```

