

Analysis at the discrete level of the low Mach problem with porosity: the triangular and the cartesian cases

Jonathan Jung (LRC-Manon, Paris 6)

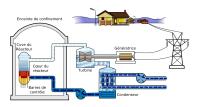
Collaborators : Stéphane Dellacherie (CEA, Saclay & LRC-Manon) Pascal Omnes (CEA, Saclay & Université Paris 13)

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Linear wave equation with porosity Numerical problem Numerical scheme

#### Study case :

• Nuclear core reactor.



#### Properties of the flow :

- Flow with variable cross-section (porosity).
- Liquid-gaz flow.
- Compressible flow.
- Low Mach number

$$|u| \ll c$$
  
$$\Leftrightarrow M := \frac{|u|}{c} \ll 1.$$

#### Aim :

• Develop a "compressible" numerical scheme that is accurate at low Mach number.

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## **Barotropic Euler equations**

• Barotropic Euler equations with porosity

$$\begin{cases} \partial_t(\alpha\rho) + \nabla \cdot (\alpha\rho \mathbf{u}) = 0, \\ \partial_t(\alpha\rho \mathbf{u}) + \nabla \cdot (\alpha\rho \mathbf{u} \otimes \mathbf{u}) + \alpha\nabla p = 0, \end{cases}$$

where  $\alpha \in [\alpha_{\min}, 1]$  is the porosity, where  $\alpha_{\min} > 0$ .

• Dimensionless : we introduce  $\tilde{x} = \frac{x}{L}$ ,  $\tilde{y} = \frac{y}{L}$ ,  $\tilde{t} = \frac{t}{T}$ ,  $\tilde{\alpha} = \frac{\alpha}{\alpha_{c}}$ ,  $\tilde{\rho} = \frac{\rho}{\rho_0}, \ \tilde{u_x} = \frac{u_x}{u_0}, \ \tilde{u_y} = \frac{u_y}{u_0}, \ \tilde{p} = \frac{p}{\rho_0} \ \text{avec} \ u_0 = \frac{L}{T}, \ \text{we obtain}$  $\begin{cases} \partial_{\tilde{t}}(\tilde{\alpha}\tilde{\rho}) + \tilde{\nabla} \cdot (\tilde{\alpha}\tilde{\rho}\tilde{\mathbf{u}}) = 0, \\ \partial_{\tilde{t}}(\tilde{\alpha}\tilde{\rho}\tilde{\mathbf{u}}) + \tilde{\nabla} \cdot (\tilde{\alpha}\tilde{\rho}\tilde{\mathbf{u}}\otimes\tilde{\mathbf{u}}) + \frac{\tilde{\alpha}}{M^2}\nabla\tilde{p} = 0, \end{cases} \quad \text{with } M = \frac{u_0}{c_0}. \end{cases}$ • Change of variable  $\tilde{\rho} := \tilde{\rho}_{\star} \left( 1 + \frac{M}{a_{\star}} \tilde{r} \right)$ , with  $\begin{cases} a_{\star}^2 = \tilde{p}'(\tilde{\rho}_{\star}) \\ \frac{M}{\tilde{r}} \ll 1. \end{cases}$  $\begin{cases} \partial_t(\tilde{\alpha}\tilde{r}) + \tilde{\nabla} \cdot (\tilde{\alpha}\tilde{r}\tilde{\mathbf{u}}) + \frac{a_\star}{M}\tilde{\nabla} \cdot (\tilde{\alpha}\tilde{\mathbf{u}}) = 0, \\ \partial_{\tilde{t}}(\tilde{\alpha}\tilde{\mathbf{u}}) + (\tilde{\mathbf{u}}\cdot\tilde{\nabla})(\tilde{\alpha}\tilde{\mathbf{u}}) + \frac{\tilde{\alpha}}{M}\frac{\tilde{p}'(\tilde{\rho}_\star(1+\frac{M}{a_\star}\tilde{r}))}{a_\star(1+\frac{M}{\omega}\tilde{r})}\nabla\tilde{r} = 0. \end{cases}$ 

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## **Barotropic Euler equations**

• Linearization around  $(\tilde{r} = 0, \tilde{\mathbf{u}} = 0)$  : linear wave equation with porosity

$$\begin{cases} \partial_t(\alpha r) + \frac{a_\star}{M} \nabla \cdot (\alpha \mathbf{u}) = 0, \\ \partial_t(\alpha \mathbf{u}) + \frac{a_\star}{M} \alpha \nabla r = 0. \end{cases}$$

• Kernel of the spatial operator : incompressible space

$$\mathcal{E}_{\alpha} := \bigg\{ q = (r, \mathbf{u})^T \in L^2_{\alpha} \left( \mathbb{T} \right)^3 \bigg| \nabla r = 0 \text{ and } \nabla \cdot \left( \alpha \mathbf{u} \right) = 0 \bigg\}.$$

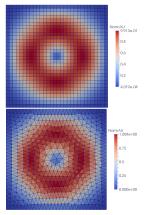
Aim :

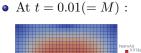
• Study the behavior of the numerical scheme with the incompressibles states  $q \in \mathcal{E}_{\alpha}$ .

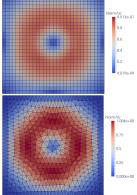
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#### Numerical problem : an initial incompressible condition $q_0 \in \mathcal{E}_{\alpha}$

• Initial condition :







#### Aims :

- Found the origin of the problem on a cartesian mesh.
- Understand the triangular case.

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## Numerical scheme

Godunov scheme on a triangular or cartesian mesh  $(\Omega_i)_{1 \le i \le N}$ 

$$\begin{cases} \frac{d}{dt} (\alpha r)_i + \frac{a_{\star}}{2M} \frac{1}{|\Omega_i|} \sum_{\Gamma_{ij} \subset \partial \Omega_i} |\Gamma_{ij}| (\alpha \mathbf{u} \cdot \mathbf{n})_{ij} = 0, \\ \frac{d}{dt} (\alpha \mathbf{u})_i + \frac{a_{\star}}{2M} \frac{\alpha_i}{|\Omega_i|} \sum_{\Gamma_{ij} \subset \partial \Omega_i} |\Gamma_{ij}| r_{ij} \mathbf{n}_{ij} = 0, \end{cases}$$

where  $(r_{ij}, (\alpha \mathbf{u} \cdot \mathbf{n})_{ij})$  is the solution of the 1D Riemann problem<sup>1</sup> in the direction  $\mathbf{n}_{ij}$  on  $\xi/t = 0$ 

$$\begin{cases} \alpha_{ij}\partial_t r_{\xi} + \frac{a_{\star}}{M}\partial_{\xi}\left((\alpha u)_{\xi}\right) = 0, \\ \partial_t\left((\alpha u)_{\xi}\right) + \frac{a_{\star}}{M}\alpha_{ij}\partial_{\xi}r_{\xi} = 0, \\ \left(r_{\xi}, (\alpha u)_{\xi}\right)\left(t = 0, \xi\right) = \begin{cases} (r_i, (\alpha \mathbf{u})_i \cdot \mathbf{n}_{ij}) & \text{si } \xi < 0, \\ \left(r_j, (\alpha \mathbf{u})_j \cdot \mathbf{n}_{ij}\right) & \text{sinon.} \end{cases}$$

1. S. Dellacherie, P. Omnes, On the Godunov scheme applied to the variable cross-section linear equation. FVCA6, (4) :313–321, 2011.

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## Numerical scheme

• The solution of the Riemann problem on  $\xi/t = 0$  is given by

$$\begin{cases} r_{ij} = \frac{r_i + r_j}{2} + \frac{1}{2\alpha_{ij}} \left( (\alpha \mathbf{u})_i - (\alpha \mathbf{u})_j \right) \cdot \mathbf{n}_{ij}, \\ \left( (\alpha \mathbf{u}) \cdot \mathbf{n} \right)_{ij} = \frac{\left( (\alpha \mathbf{u})_i + (\alpha \mathbf{u})_j \right) \cdot \mathbf{n}_{ij}}{2} + \frac{\alpha_{ij}}{2} (r_i - r_j). \end{cases}$$

• Godunov scheme on a triangular or cartesian mesh  $(\Omega_i)_{1 \le i \le N}$  [DO11]

$$\begin{cases} \frac{d}{dt} (\alpha r)_i + \frac{a_{\star}}{2M} \frac{1}{|\Omega_i|} \sum_{\Gamma_{ij} \subset \partial \Omega_i} |\Gamma_{ij}| \Big[ \big( (\alpha \mathbf{u})_i + (\alpha \mathbf{u})_j \big) \cdot \mathbf{n}_{ij} + \alpha_{ij} (r_i - r_j) \Big] = 0, \\ \frac{d}{dt} (\alpha \mathbf{u})_i + \frac{a_{\star}}{2M} \frac{\alpha_i}{|\Omega_i|} \sum_{\Gamma_{ij} \subset \partial \Omega_i} |\Gamma_{ij}| \Big[ r_i + r_j + \frac{\kappa}{\alpha_{ij}} \big( (\alpha \mathbf{u})_i - (\alpha \mathbf{u})_j \big) \cdot \mathbf{n}_{ij} \Big] \mathbf{n}_{ij} = 0 \\ \text{with } \kappa = 1. \end{cases}$$

4

### Found the origin of the problem on a cartesian mesh

Modified equation on a cartesian mesh :

• The Godunov scheme on a cartesian mesh  $\Omega_{i,j}$  for  $\alpha r$  gives us

$$\partial_t (\alpha r)_{i,j} + \frac{a_{\star}}{M} \frac{(\alpha u_x)_{i+1,j} - (\alpha u_x)_{i-1,j}}{2\Delta x} + \frac{a_{\star}}{M} \frac{(\alpha u_y)_{i,j+1} - (\alpha u_y)_{i,j-1}}{2\Delta y} \\ = \frac{a_{\star}}{2M\Delta x} \left( \alpha_{i+\frac{1}{2},j} \left( r_{i+1,j} - r_{i,j} \right) - \alpha_{i-\frac{1}{2},j} \left( r_{i,j} - r_{i-1,j} \right) \right) \\ + \frac{a_{\star}}{2M\Delta y} \left( \alpha_{i,j+\frac{1}{2}} \left( r_{i,j+1} - r_{i,j} \right) - \alpha_{i,j-\frac{1}{2}} \left( r_{i,j} - r_{i,j-1} \right) \right).$$

• Then, the first order modified equation for  $\alpha r$  is

$$\partial_t(\alpha r) + \frac{a_\star}{M} \nabla \cdot (\alpha \mathbf{u}) = \frac{a_\star \Delta x}{2M} \partial_x(\alpha \partial_x r) + \frac{a_\star \Delta y}{2M} \partial_y(\alpha \partial_y r).$$

Modified equation on a cartesian mesh Discrete study on a cartesian mesh Discrete study of the triangular case

## Modified equation on a cartesian mesh

• We use the same method for  $\alpha \mathbf{u}$  and we obtain the modified system

$$\partial_t(\alpha r) + \frac{a_\star}{M} \nabla \cdot (\alpha \mathbf{u}) - \frac{a_\star \Delta x}{2M} \partial_x(\alpha \partial_x r) - \frac{a_\star \Delta y}{2M} \partial_y(\alpha \partial_y r) = 0$$

$$\partial_t(\alpha \mathbf{u}) + \frac{a_\star}{M} \alpha \nabla r - \begin{pmatrix} \kappa \alpha \frac{a_\star \Delta x}{2M} \partial_x \left( \frac{1}{\alpha} \partial_x(\alpha u_x) \right) \\ \kappa \alpha \frac{a_\star \Delta y}{2M} \partial_y \left( \frac{1}{\alpha} \partial_y(\alpha u_y) \right) \end{pmatrix} = 0$$

with  $\kappa = 1$ . We write it as

$$\partial_t(\alpha q) + \frac{\mathcal{L}_{\kappa,\alpha}}{M}(q) = 0 \quad \text{with} \quad \mathcal{L}_{\kappa,\alpha} = L_\alpha - MB_{\kappa,\alpha}.$$

• What is the relation between Ker  $\mathcal{L}_{\kappa,\alpha}$  and  $\mathcal{E}_{\alpha}$ ?

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## Kernel of the modified equation

#### Proposition

• If  $\kappa > 0$ , we have

$$Ker \mathcal{L}_{\kappa>0,\alpha} = \left\{ q := (r, \boldsymbol{u})^T | \nabla r = 0 \text{ and } \partial_x(\alpha u_x) = \partial_y(\alpha u_y) = 0 \right\}$$
$$\subseteq \mathcal{E}_{\alpha}.$$

2) If 
$$\kappa = 0$$
, we have  $\operatorname{Ker} \mathcal{L}_{\kappa=0,\alpha} = \mathcal{E}_{\alpha}$ .

Conclusion of the study of the continuous case :

• Substitute  $\kappa = 1$  by  $\kappa = 0$  seams to allow to the Godunov scheme to preserve the incompressible states  $q^0 \in \mathcal{E}_{\alpha}$  on cartesian meshes.

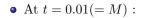
#### To do :

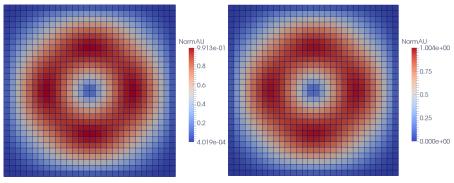
• Test this correction  $(\kappa = 0)$  at the discret level.

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## Test of the low Mach correction $\kappa = 0$

• Initial condition  $q^0 \in \mathcal{E}_{\alpha}$ :





#### Aims :

- Study the problem at the discrete level.
- Study the case of a triangular mesh.

## Discrete study

- We define the spaces  $\mathcal{E}_{\alpha}^{\bigtriangleup}$  and  $\mathcal{E}_{\alpha}^{\Box}$  associated to the incompressible space  $\mathcal{E}_{\alpha}$  on a triangular and a cartesian mesh.
- Recall the Godunov scheme on a triangular or cartesian mesh  $(\Omega_i)_{1 \le i \le N}$  [DO11]

$$\begin{cases} \frac{d}{dt} (\alpha r)_i + \frac{a_{\star}}{2M} \frac{1}{|\Omega_i|} \sum_{\Gamma_{ij} \subset \partial \Omega_i} |\Gamma_{ij}| \Big[ \left( (\alpha \mathbf{u})_i + (\alpha \mathbf{u})_j \right) \cdot \mathbf{n}_{ij} + \alpha_{ij} (r_i - r_j) \Big] = 0, \\ \left( \frac{d}{dt} (\alpha \mathbf{u})_i + \frac{a_{\star}}{2M} \frac{\alpha_i}{|\Omega_i|} \sum_{\Gamma_{ij} \subset \partial \Omega_i} |\Gamma_{ij}| \Big[ r_i + r_j + \frac{\kappa}{\alpha_{ij}} \big( (\alpha \mathbf{u})_i - (\alpha \mathbf{u})_j \big) \cdot \mathbf{n}_{ij} \Big] \mathbf{n}_{ij} = 0 \\ \text{with } \kappa = 1. \end{cases}$$

• We write it as

$$\frac{d}{dt}(\alpha q_h) + \frac{\mathbb{L}_{\kappa,\alpha}^h}{M}(q_h) = 0,$$

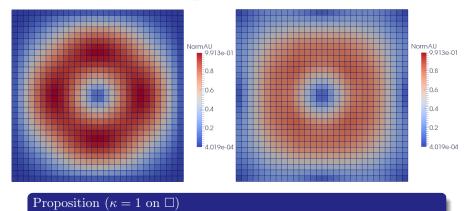
where  $q_h = (r_i, \mathbf{u}_i)^T$ .

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#### Gudunov scheme $(\kappa=1)$ on a cartesian mesh :

• Initial condition  $q^0 \in \mathcal{E}^{\square}_{\alpha}$ :

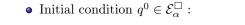
• At 
$$t = 0.01(= M)$$
 :



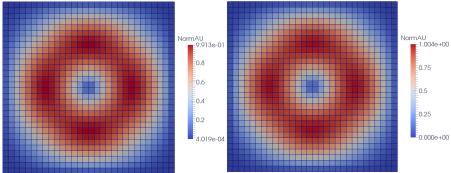
$$Ker \mathbb{L}^h_{\kappa=1,\alpha} \subsetneq \mathcal{E}^\square_\alpha.$$

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#### Low Mach scheme $(\kappa = 0)$ on a cartesian mesh :



• At 
$$t = 0.01(=M)$$
 :



Proposition ( $\kappa = 0$  on  $\Box$ )

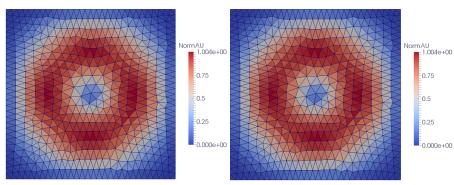
$$Ker \mathbb{L}^h_{\kappa=0,\alpha} = \mathcal{E}^\square_\alpha.$$

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#### Godunov scheme $(\kappa = 1)$ on a triangular mesh :

• Initial condition  $q^0 \in \mathcal{E}_{\alpha}^{\Delta}$ :

• At t = 0.01(= M) :



Proposition ( $\kappa = 1$  on  $\triangle$ )

$$Ker \mathbb{L}^h_{\kappa=1,\alpha} = \mathcal{E}^{\triangle}_{\alpha}.$$

# Conclusion on the discrete study of the kernel of the Godunov scheme

#### Conclusion:

- The Godunov scheme (κ = 1) does not preserve some incompressible states 𝔅<sup>□</sup><sub>α</sub> on a cartesian mesh.
- The low Mach scheme (κ = 0) preserves the incompressible states 𝔅<sup>□</sup><sub>α</sub> on a cartesian mesh.
- The Godunov scheme ( $\kappa = 1$ ) preserves the incompressible states  $\mathcal{E}_{\alpha}^{\triangle}$  on a triangular mesh.

#### BUT :

- We wish a correction that allows to obtain the Godunov scheme when the Mach number tends to 1.
- What happens if the initial condition  $q^0 \notin \mathcal{E}_{\alpha}$ ?
- The study of the kernel  $\mathcal{E}_{\alpha}$  is not sufficient.

## Hodge decomposition and projection on $\mathcal{E}_{\alpha}$

#### How can we split a state $q \notin \mathcal{E}_{\alpha}$ ?

#### Theorem

Assume that  $\alpha \in [\alpha_{\min}, \alpha_{\max}]$  with  $\alpha_{\min} > 0$ . We build a Hodge decomposition on the weighted spaces

$$\mathcal{E}_{\alpha} \oplus \mathcal{E}_{\alpha}^{\perp} = L_{\alpha}^{2} \left( \mathbb{T} \right)^{3},$$

where the acoustic space  $\mathcal{E}_{\alpha}^{\perp}$  is given by

$$\mathcal{E}_{\alpha}^{\perp} = \left\{ q = (r, \boldsymbol{u})^{T} \in L_{\alpha}^{2} \left( \mathbb{T} \right)^{3} \Big| \int_{\mathbb{T}} r \alpha dx = 0 \text{ and } \exists \phi \in H_{\alpha}^{1} \left( \mathbb{T} \right), \boldsymbol{u} = \nabla \phi \right\}$$

#### Definition

The Hodge decomposition allows to define an orthogonale projection  $\mathbb{T}^2$  (TT)<sup>3</sup>

$$\mathbb{P}_{\alpha}: \ L^{2}_{\alpha}\left(\mathbb{T}\right)^{3} \longrightarrow \mathcal{E}_{\alpha}$$
$$q \longmapsto \mathbb{P}_{\alpha}q$$

Structure of the solution of the linear wave equation

Linear wave equation with porosity

$$\begin{cases} \partial_t(\alpha r) + \frac{a_\star}{M} \nabla \cdot (\alpha \mathbf{u}) = 0, \\ \partial_t(\alpha \mathbf{u}) + \frac{a_\star}{M} \alpha \nabla r = 0. \end{cases}$$

#### Proposition

If q is a solution of the linear wave equation with porosity with an initial condition  $q^0$ , we have

$$\forall q^0 \in \mathcal{E}_{\alpha}, \quad q(t \ge 0) = q^0 \in \mathcal{E}_{\alpha} \quad et \quad \forall q^0 \in \mathcal{E}_{\alpha}^{\perp}, \quad q(t \ge 0) \in \mathcal{E}_{\alpha}^{\perp}.$$

#### Corollary

The solution q of the linear wave equation with porosity with an initial condition  $q^0$  can be written as

$$q = \mathbb{P}_{\alpha}q^{0} + (q - \mathbb{P}_{\alpha}q^{0}) \in \mathcal{E}_{\alpha} + \mathcal{E}_{\alpha}^{\perp}.$$

## Structure of the solution of the linear wave equation

Linear wave equation with porosity

$$\begin{cases} \partial_t(\alpha r) + \frac{a_\star}{M} \nabla \cdot (\alpha \mathbf{u}) = 0, \\ \partial_t(\alpha \mathbf{u}) + \frac{a_\star}{M} \alpha \nabla r = 0. \end{cases}$$

#### Proposition

The energy of the solution q of the linear wave equation with porosity satisfies

$$\frac{d}{dt} \|q\|_{L^2_{\alpha}}^2 = 0.$$

#### Corollary

The solution q of the linear wave equation with porosity and with an initial condition  $q^0$  satisfies

$$\forall C>0, \ \|q^0-\mathbb{P}_{\alpha}q^0\|_{L^2_{\alpha}}\leq CM \Rightarrow \forall t\geq 0, \ \|q-\mathbb{P}_{\alpha}q^0\|_{L^2_{\alpha}}(t)\leq CM.$$

## Accurate schemes at low Mach number

- We transcribe this property at the discrete level for short time.
- We build Hodge decompositions on triangular and cartesian meshes.
- We obtain discrete orthogonal projections  $\mathbb{P}^h_{\alpha}$  on  $\mathcal{E}^{\square}_{\alpha}$  and  $\mathcal{E}^{\triangle}_{\alpha}$ .

#### Definition

A scheme is accurate at low Mach number if the solution  $q_h$  given by the scheme satisfies

$$\begin{aligned} \forall C_1, C_2 > 0, \ \exists C_3(C_1, C_2) > 0, \ \|q_h^0 - \mathbb{P}^h_\alpha q_h^0\|_{l^2_\alpha} &= C_1 M \\ \Rightarrow \forall t \in [0; C_2 M], \ \|q_h - \mathbb{P}^h_\alpha q_h^0\|_{l^2_\alpha}(t) \le C_3 M, \end{aligned}$$

where  $C_3$  does not depend on M.

#### Initial condition :

- $a_{\star} = 1$ .
- $M = 10^{-4}$ .
- $q_h^0 = q_{h,1}^0 + \mathbf{M} q_{h,2}^0$  with

$$\begin{cases} r_{h,1}^0(x,y) = 1, \\ (\alpha \mathbf{u}_1)_h^0 = \nabla_h \times \psi_h, \end{cases} \Rightarrow q_{h,1}^0 \in \mathcal{E}_{\alpha}^h \end{cases}$$

and

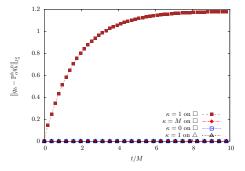
$$\begin{cases} r_{h,2}^{0}(x,y) = 0, \\ \mathbf{u}_{h,2}^{0} = \nabla_{h}\phi_{h}, \quad \Rightarrow q_{h,2}^{0} \in \left(\mathcal{E}_{\alpha}^{h}\right)^{\perp} \\ \|q_{h,2}^{0}\|_{l_{\alpha}^{2}} = 1, \end{cases}$$

then

$$\|q_h^0 - \mathbb{P}_{\alpha} q_h^0\|_{l_{\alpha}^2} = \|Mq_{h,2}^0\|_{l_{\alpha}^2} = M = O(M).$$

• We plot  $||q_h - \mathbb{P}_{\alpha} q_h^0||_{l^2_{\alpha}}(t)$  as a fonction of the time.

#### Cartesian mesh with $\Delta x = \Delta y = 0.02$ and $M = 0.0001 \ll \Delta x$ :

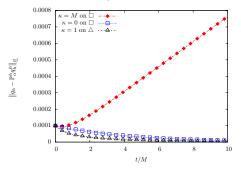


#### Theorem ( $\kappa = 1$ on $\Box$ )

 $\begin{aligned} \forall C_1 > 0, \ \exists C_2(C_1) > 0, \ \exists C_3(C_1) > 0, \ \|q_h^0 - \mathbb{P}^{h,\square}_{\alpha} q_h^0\|_{l^2_{\alpha}} = C_1 M \\ \Rightarrow \forall t \ge C_2 M, \ \|q_h - \mathbb{P}^{h,\square}_{\alpha} q_h^0\|_{l^2_{\alpha}}(t) \ge C_3 \min(\Delta x, \Delta y), \end{aligned}$ 

for all  $M \leq \frac{C_3}{C_1} \min(\Delta x, \Delta y)$ .

#### Cartesian mesh with $\Delta x = \Delta y = 0.02$ and $M = 0.0001 \ll \Delta x$ :

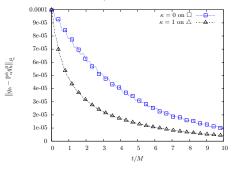


#### Theorem ( $\kappa = M$ on $\Box$ )

 $\begin{aligned} \forall C_1, C_2 > 0, \ \exists C_3(C_1, C_2) > 0, \ \|q_h^0 - \mathbb{P}^{h, \square}_{\alpha} q_h^0\|_{l^2_{\alpha}} &= C_1 M \\ \Rightarrow \forall t \in [0; C_2 M], \ \|q_h - \mathbb{P}^{h, \square}_{\alpha} q_h^0\|_{l^2_{\alpha}}(t) \le C_3 M, \end{aligned}$ 

where  $C_3$  does not depend on M.

#### Cartesian mesh with $\Delta x = \Delta y = 0.02$ and $M = 0.0001 \ll \Delta x$ :

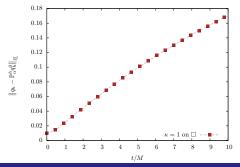


#### Theorem ( $\kappa = 1$ on $\triangle$ et $\kappa = 0$ sur $\Box$ )

$$\begin{aligned} \forall C_1, C_2 > 0, \ \exists C_3(C_1, C_2) > 0, \ \|q_h^0 - \mathbb{P}^h_\alpha q_h^0\|_{l^2_\alpha} &= C_1 M \\ \Rightarrow \forall t \ge 0, \ \|q_h - \mathbb{P}^h_\alpha q_h^0\|_{l^2_\alpha}(t) \le C_3 M, \end{aligned}$$

where  $C_3$  does not depend on M.

#### Cartesian mesh on $\Delta x = \Delta y = 0.0033$ and $M = 0.01 \gg \Delta x$ :



Theorem ( $\kappa = 1$  on  $\Box$ )

$$\begin{aligned} \forall C_0, C_1, C_2 > 0, \exists C_3(C_0, C_1, C_2) > 0, \begin{cases} \Delta x \le C_0 M, \ et \ \Delta y \le C_0 M, \\ \|q_h^0 - \mathbb{P}_{\alpha}^h q_h^0\|_{l^2_{\alpha}} = C_1 M \\ \Rightarrow \forall t \in [0; C_2 M], \ \|q_h - \mathbb{P}_{\alpha}^h q_h^0\|_{l^2_{\alpha}} (t) \le C_3 M, \end{aligned}$$

where  $C_3$  does not depend on M,  $\Delta x$  and  $\Delta y$ .

## Conclusion of the linear case

#### Triangular mesh :

• The Godunov scheme  $(\kappa = 1)$  is accurate at low Mach.

Cartesian mesh :

- The Godunov scheme  $(\kappa = 1)$ 
  - is not accurate at low Mach number if  $M \ll \min(\Delta x, \Delta y)$ .
  - is accurate at low Mach number if  $M \gg \min(\Delta x, \Delta y)$ .

• Two corrections for low Mach flows :

$$F^{Cor}(W_i, W_j) = F^{God}(W_i, W_j) - \frac{(1-\kappa)a_{\star}\alpha_i}{2M\alpha_{ij}} \begin{pmatrix} 0 \\ \left[ \left( (\alpha \mathbf{u})_i - (\alpha \mathbf{u})_j \right) \cdot \mathbf{n}_{ij} \right] \mathbf{n}_{ij} \end{pmatrix}$$

- $\kappa = 0$  (low Mach correction) : accurate at low Mach,
- $\overline{\kappa = \min(M, 1)}$  (all Mach correction) : accurate at low Mach and allows to obtain the Godunov scheme for  $M \ge 1$ .

Next step :

• Test the different schemes in the non-linear case.

# Correction at low Mach number in the non-linear case with $\alpha = 1$

Barotropic Euler equations :

$$\begin{cases} \partial_t \rho + \nabla \cdot (\rho \mathbf{u}) = 0, \\ \partial_t (\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u}) + \nabla p = 0. \end{cases}$$

Nous notons  $W = (\rho, \rho \mathbf{u})^T$ . The numerical scheme can be written as

$$\frac{d}{dt}W_i + \frac{1}{|\Omega_i|} \sum_{\Gamma_{ij} \subset \partial \Omega_i} |\Gamma_{ij}| F(W_i, W_j, \mathbf{n}_{ij}) = 0.$$

The **low Mach** and the **all Mach** corrections consist to replace the flux  $F(W_i, W_j, \mathbf{n}_{ij})$  with

$$F^{Cor}(W_i, W_j) = F^{Roe}(W_i, W_j) - \frac{(1 - \kappa_{ij})\rho_{ij}c_{ij}}{2} \begin{pmatrix} 0\\ [(\mathbf{u}_i - \mathbf{u}_j) \cdot \mathbf{n}_{ij}] \mathbf{n}_{ij} \end{pmatrix}$$
  
where respectively  $\kappa_{ij} = 0$  or  $\kappa_{ij} = \min\left(1, \frac{|u_{ij}|}{c_{ij}}\right)$ .

## 4 shocks

• The initial state is given by

$$(\rho, u_x, u_y)(x, y) = \begin{cases} (0.1380, 1.206, 1.206), & \text{for } x < 0.5, & y < 0.5\\ (0.5323, 0.000.1.206), & \text{for } x > 0.5, & y < 0.5\\ (0.5323, 1.206, 0.000), & \text{for } x < 0.5, & y > 0.5\\ (1.5000, 0.000, 0.000), & \text{for } x > 0.5, & y > 0.5 \end{cases}$$

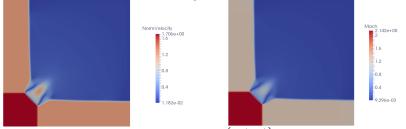
on the domain  $[0,1] \times [0,1]$ .

- Neumann boundary conditions.
- Final time of computation :  $t_{final} = 0.4s$ .
- Tools :
  - Mesh : the software Salome,
  - Code : Librairy C++ CDMATH (http://www.cdmath.jimdo.com).

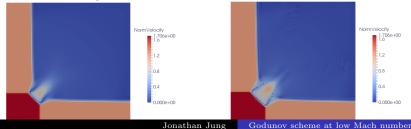
#### 4 shocks:

29/37

• Reference solution (Roe ( $\kappa_{ij} = 1$ ) on a 200 × 200 cartesian grid) :

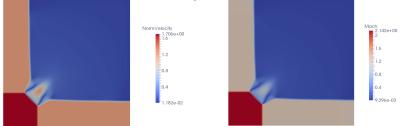


• Roe with  $\kappa_{ij} = 1$  and  $\kappa_{ij} = \min\left(1, \frac{|u_{ij}|}{c_{ij}}\right)$  on a  $100 \times 100$  cartesian grid :



#### 4 shocks:

• Reference solution (Roe  $(\kappa_{ij} = 1)$  on a 200 × 200 cartesian grid) :



• Roe with  $\kappa_{ij} = 0$  on a cartesian and with  $\kappa_{ij} = 1$  on a triangular mesh :

## The scheme crashes with $\kappa_{ij} = 0!$







Jonathan Jung

Godunov scheme at low Mach number

#### Vortex :

- We use a perfect gaz law.
- The initial state is given by

$$\begin{split} \rho &= 1, \quad p = 1000 \\ \text{et} \quad \mathbf{u} &= \nabla \times \psi \quad \text{avec} \quad \psi(x,y) = \frac{1}{\pi} \sin^2(\pi x) \sin^2(\pi y) \end{split}$$

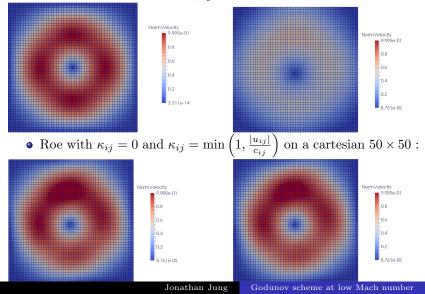
on the domain  $[0,1]\times [0,1].$ 

- Wall boundary conditions.
- Final time of computation :  $t_{final} = 0.125s$ .

#### Vortex :

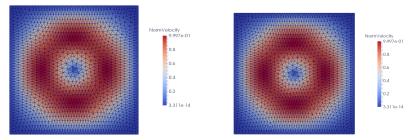
32/37

• Initial condition and Roe ( $\kappa_{ij} = 1$ ) on a 50 × 50 cartesian grid :



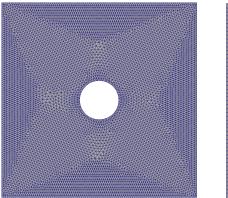
#### Vortex :

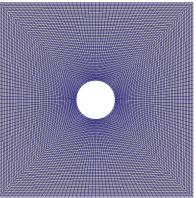
• Initial condition and Roe with  $\kappa_{ij} = 1$  on a triangular mesh :



#### Steady flow around a cylinder

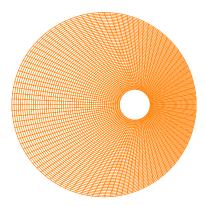
• An advantage of CDMATH is that the code can be run on very complex geometry build with Salome.

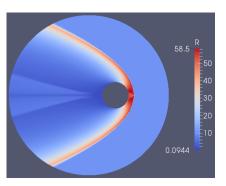




#### Carbuncle phenomena : supersonic flow around a cylinder

• An advantage of CDMATH is that the code can be run on very complex geometry build with Salome.





## Final conclusion and perspective

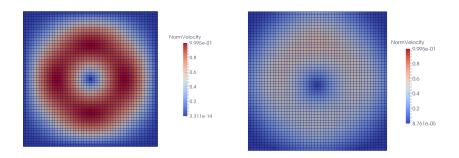
#### Conclusion :

- We constat the accuracy at low Mach number of finite volume schemes on triangular meshes in the linear and non-linear cases.
- We constat the inaccuracy at low Mach number of the finite volume schemes on cartesian meshes in the linear and non-linear cases.
- The study of the linear case allows to propose a correction that gives an accurate scheme at low Mach number and gives the Godunov scheme when  $M \ge 1$  on cartesian meshes.

#### Perpectives :

- Test the scheme with a non-constant fonction  $\alpha$  in the non-linear case.
- Study the stability of the corrected scheme in the non-linear case.

#### Thank you for your attention!



S. Dellacherie, P. Omnes. On the Godunov scheme applied to the variable cross-section linear equation. FVCA6, (4):313–321, 2011.