

## Model

We consider the flow of a mixture of two compressible fluids (a gas and a liquid, for instance) in a cross-section duct. The model is the following:

$$\partial_t W + \partial_x F(W) = S(W) \quad (1)$$

where the vector of conservative variables is:

$$W = (A\rho, A\rho u, A\rho E, A\rho\varphi, A)^T, \quad (2)$$

the conservative flux is:

$$F(W) = (A\rho u, A(\rho u^2 + p), A(\rho E + p)u, A\rho\varphi u, 0)^T, \quad (3)$$

and the non-conservative source term is:

$$S = (0, p\partial_x A, 0, 0, 0). \quad (4)$$

Without loss of generality, we consider a stiffened gas pressure law:

$$p(\rho, e, \varphi) = (\gamma(\varphi) - 1)\rho e - \gamma(\varphi)\pi(\varphi). \quad (5)$$

## Numerical scheme

### • Finite volume scheme

The system (??) is approached by a **finite volume scheme** on cells  $[x_{i-1/2}, x_{i+1/2}]$ ,  $i \in \mathbb{Z}$ . We note  $\tau$  the time step and  $\Delta x_i = x_{i+1/2} - x_{i-1/2}$  the size of the cell  $i$ . We note  $W_i^n$  the vector of conservative variables on cell  $i$  at time  $t_n$ . The cross-section  $A$  is approximated by a piecewise constant function,  $A = A_i$  on cell  $i$ .

We consider an **Arbitrary Lagrangian Eulerian** (ALE) approach. The boundary  $x_{i+1/2}^n$  can move at the speed  $v_{i+1/2}^n$  between  $t_n$  and  $t_{n+1}$ :

$$x_{i+1/2}^{n+1,-} = x_{i+1/2}^n + \tau v_{i+1/2}^n. \quad (6)$$

We define an ALE numerical flux:

$$F(W_L, W_R, v^\pm) := F(W(W_L, W_R, v^\pm)) - vW(W_L, W_R, v^\pm) \quad (7)$$

where  $W(W_L, W_R, v^\pm)$  is obtained with an approximated Riemann solver described in a next part.

If  $v_{i+1/2}^n \leq 0$  and  $v_{i-1/2}^n \geq 0$ , the ALE scheme is:

$$\Delta x_i^{n+1} W_i^{n+1,-} - \Delta x_i^n W_i^n + \tau \left( F(W_i^n, W_{i+1}^n, v_{i+1/2}^{n,-}) - F(W_{i-1}^n, W_i^n, v_{i-1/2}^{n,+}) \right) = 0. \quad (8)$$

To take into account the variable section, if  $v_{i+1/2}^n > 0$  we have to add the following term on the left of the equation above

$$\tau \left( F(W_i^n, W_{i+1}^n, 0^-) - F(W_i^n, W_{i+1}^n, 0^+) \right), \quad (9)$$

and if  $v_{i-1/2}^n < 0$ , we add:

$$\tau \left( F(W_{i-1}^n, W_i^n, 0^-) - F(W_{i-1}^n, W_i^n, 0^+) \right). \quad (10)$$

### • Computing the interface speed $v_{i+1/2}^n$

When initial data satisfy  $\varphi \in \{0, 1\}$ , the algorithm verifies

- If we are not at the interface, i.e. if  $\varphi_L = \varphi_R$ , we take  $v = 0$ .
- If we are at the interface, i.e. if  $\varphi_L \neq \varphi_R$ , we use an exact Riemann solver to compute  $u^*(W_L, W_R)$  and  $p^*(W_L, W_R)$  which present no jump at the contact discontinuity. We take  $v = u^*(W_L, W_R)$ ,  $A^* = A_L$  if  $v < 0$  and  $A^* = A_R$  if  $v > 0$ . The ALE flux becomes Lagrangian and takes the following form:

$$F(W_L, W_R, v^\pm) = (0, A^* p^*, A^* u^* p^*, 0, -A^* u^*)^T. \quad (11)$$

### • Well-balanced solver for $W(W_L, W_R, 0^\pm)$

As the Riemann invariants associated to the stationary wave are  $\varphi$ ,  $s = (p + \pi(\varphi))\rho^{-\gamma(\varphi)}$ ,  $Q = \rho Au$  and  $H = E + \frac{p}{\rho}$ , the idea is to use a **VFRoe scheme [1] in  $Z = (A, \varphi, s, Q, H)^T$** .

We then obtain  $Z(W_L, W_R, 0^\pm)$  from which we get  $W(W_L, W_R, 0^\pm)$ . In some cases, this change of variables is not bijective: we have to adapt our approach.

### • Entropy correction

A VFRoe scheme approaches badly the waves of relaxation crossing the interface  $x = 0$  and authorizes in these points non-physical shocks. It is the case when an eigenvalue associated to a non-linear k-field verifies the following inequalities:  $\lambda_k(W_i^n) \leq 0 \leq \lambda_{k+1}(W_{i+1}^n)$ .

We replace the numerical flux  $F$  by:

$$G(W_i^n, W_{i+1}^n, 0^\pm) = F(W_i^n, W_{i+1}^n, 0^\pm) - \min_k (|\lambda_k(W_i^n)|, |\lambda_{k+1}(W_{i+1}^n)|) (W_{i+1}^n - W_i^n) / 2.$$

### • Glimm remap

We go back to the original grid by the Glimm procedure [2]. We construct a sequence of pseudo-random  $\omega_n \in [0, 1[$ , and we take:

$$W_i^{n+1} = \begin{cases} W_{i-1}^{n+1,-}, & \text{si } \omega_n < \frac{\tau_n}{\Delta x_i} \max(v_{i-1/2}^n, 0), \\ W_i^{n+1,-}, & \text{si } \frac{\tau_n}{\Delta x_i} \max(v_{i-1/2}^n, 0) \leq \omega_n \leq 1 + \frac{\tau_n}{\Delta x_i} \min(v_{i+1/2}^n, 0), \\ W_{i+1}^{n+1,-}, & \text{si } \omega_n > 1 + \frac{\tau_n}{\Delta x_i} \min(v_{i+1/2}^n, 0). \end{cases} \quad (12)$$

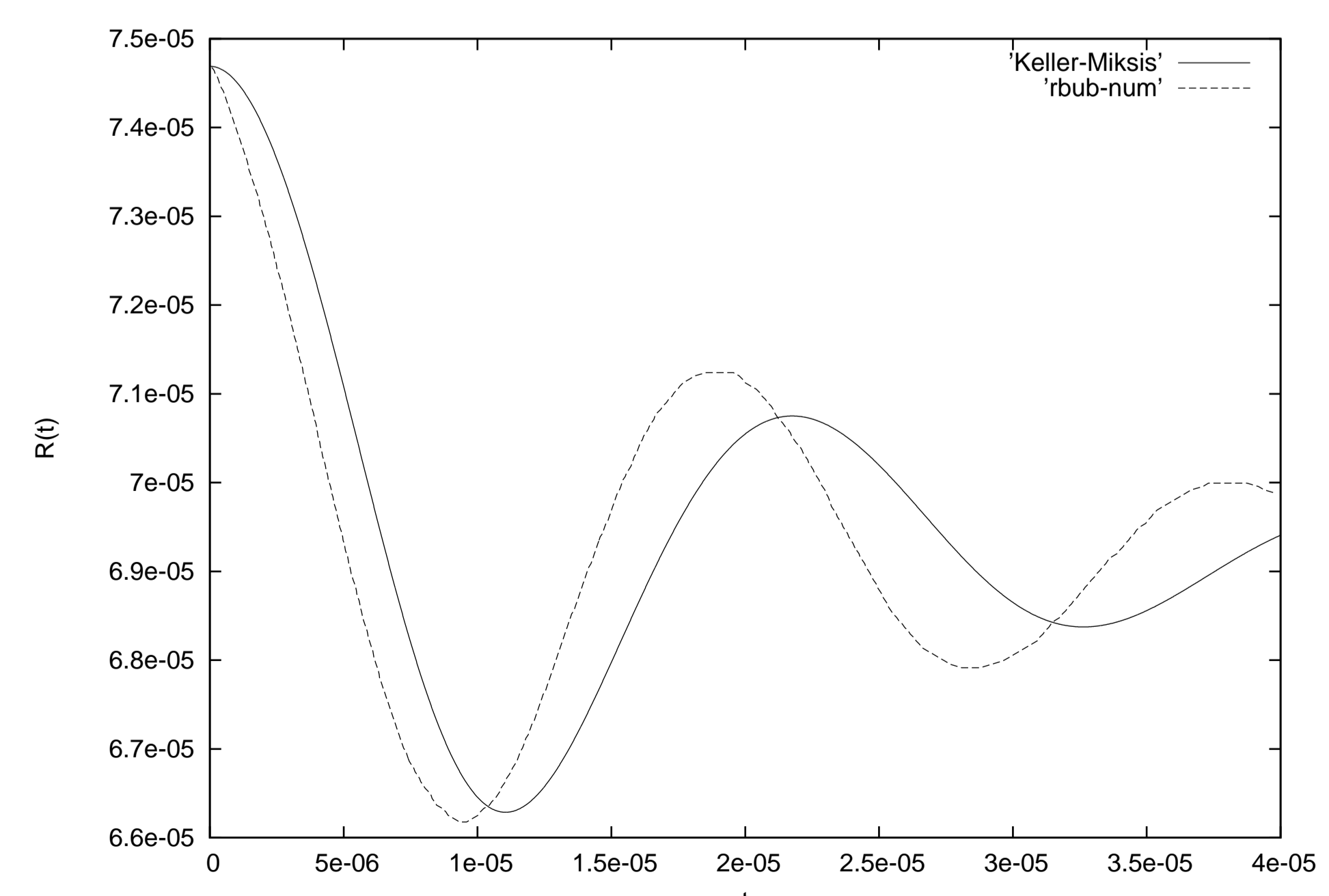
### • Properties of the scheme

The constructed scheme has the following properties:

- it is well-balanced, meaning that **it preserves exactly all stationary states** (i.e. initial data for which the quantities  $\varphi$ ,  $s$ ,  $Q$ ,  $H$  are constant);
- if the fraction of gas  $\varphi$  takes only the two values  $0$  or  $1$ , this property is exactly preserved at any time.

## Implosion of a bubble

We valid our model by simulating the collapse of a spherical bubble of gas in liquid water. In that purpose, we assume an invariance under rotation and we adopt a 1D approach with a variable cross section  $A(x) = 4\pi x^2$ . We plot the radius of the bubble that we compare to the ODE model of Keller-Miksis [3], we obtain:



### Bibliography

[1] P. HELLUY, J.-M. HÉRARD AND H. MATHIS, *A well-balanced approximate Riemann solver for variable cross-section compressible flows.*, Computational Fluid Dynamics, June 2009.

[2] C. CHALONS AND F. COQUEL, *Computing material fronts with Lagrange-Projection approach.*, HYP2010 Proc. <http://hal.archives-ouvertes.fr/hal-00548938/fr/>.