

A low Mach correction for the Godunov scheme applied to the linear wave equation with porosity

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Study case :

• Nuclear reactor core.



Properties of the flow :

- Flow with variable cross section (porosity).
- Liquid-gas flow.
- Compressible flow.
- Low Mach number

$$\begin{split} |u| \ll c \\ \Leftrightarrow M := \frac{|u|}{c} \ll 1. \end{split}$$

Aim :

• Develop a "compressible" numerical scheme that is accurate at low Mach number.

Linear wave equations with porosity Properties

Numerical problems : an initial stationary condition



• After 1000 iterations :



Aims :

- Understand the influence of the cell geometry.
- Propose a correction on cartesian meshes.

Linear wave equations with porosity (or void fraction)

• Dimensionless barotropic Euler equations with porosity (or void fraction)

$$\begin{cases} \partial_t(\alpha\rho) + \nabla \cdot (\alpha\rho \mathbf{u}) = 0, \\ \partial_t(\alpha\rho \mathbf{u}) + \nabla \cdot (\alpha\rho \mathbf{u} \otimes \mathbf{u}) + \frac{\alpha}{M^2} \nabla p = 0, \end{cases}$$

where $\alpha \in [\alpha_{\min}, 1]$ is the porosity, where $\alpha_{\min} > 0$ is a constant that does not depend on M.

• Change of variable $\rho := \rho_{\star} \left(1 + \frac{M}{a_{\star}} r \right)$, with $\begin{cases} a_{\star}^2 = p'(\rho_{\star}) \\ \frac{M}{a_{\star}} r \ll 1. \end{cases}$ Linearization around $(\rho_{\star} = cst, \mathbf{u}_{\star} = 0)$:

$$\begin{cases} \partial_t(\alpha r) + \frac{a_\star}{M} \nabla \cdot (\alpha \mathbf{u}) = 0, \\ \partial_t(\alpha \mathbf{u}) + \frac{a_\star}{M} \alpha \nabla r = 0. \end{cases}$$

• Kernel of the spatial operator : **incompressible space** $\mathcal{E}_{\alpha} := \left\{ q = (r, \mathbf{u})^T \in L^2_{\alpha} \left(\mathbb{T} \right)^3 \middle| \nabla r = 0 \text{ and } \nabla \cdot \left(\alpha \mathbf{u} \right) = 0 \right\}.$

Linear wave equations with porosity **Properties**

Theorem

We can build a Hodge decomposition on the weighted spaces

$$\mathcal{E}_{\alpha} \oplus \mathcal{E}_{\alpha}^{\perp} = L_{\alpha}^{2} \left(\mathbb{T} \right)^{3},$$

where the **acoustic space** $\mathcal{E}_{\alpha}^{\perp}$ is defined by

$$\mathcal{E}_{\alpha}^{\perp} = \left\{ q = (r, \boldsymbol{u})^T \in L^2_{\alpha} \left(\mathbb{T} \right)^3 \Big| \int_{\mathbb{T}} r \alpha dx = 0 \ and \ \exists \phi \in H^1_{\alpha} \left(\mathbb{T} \right), \boldsymbol{u} = \nabla \phi \right\}.$$

Proposition

If q is solution of the linear wave equation with porosity (or void fraction) with an initial condition q^0 , we have

•
$$\forall q^0 \in \mathcal{E}_{\alpha}, \quad q(t \ge 0) \in \mathcal{E}_{\alpha};$$

• $\forall q^0 \in \mathcal{E}^{\perp}_{\alpha}, \quad q(t \ge 0) \in \mathcal{E}^{\perp}_{\alpha}.$

Introduction **Godunov scheme and meshes** Godunov scheme and well-prepared states **Triangular mesh**

Godunov scheme

Godunov scheme on a triangular or a cartesian mesh $(\Omega_i)_{1 \le i \le N}$

$$\begin{cases} \frac{d}{dt} (\alpha r)_i + \frac{a_{\star}}{2M} \frac{1}{|\Omega_i|} \sum_{\Gamma_{ij} \subset \partial \Omega_i} |\Gamma_{ij}| (\alpha \mathbf{u} \cdot \mathbf{n})_{ij} = 0, \\ \frac{d}{dt} (\alpha \mathbf{u})_i + \frac{a_{\star}}{2M} \frac{\alpha_i}{|\Omega_i|} \sum_{\Gamma_{ij} \subset \partial \Omega_i} |\Gamma_{ij}| r_{ij} \mathbf{n}_{ij} = 0, \end{cases}$$

where $(r_{ij}, (\alpha \mathbf{u} \cdot \mathbf{n})_{ij})$ is the solution of the 1*D* Riemann problem¹ in the \mathbf{n}_{ij} direction

$$\begin{cases} \alpha_{ij}\partial_t r_{\xi} + \frac{a_{\star}}{M}\partial_{\xi}\left((\alpha u)_{\xi}\right) = 0, \\ \partial_t\left((\alpha u)_{\xi}\right) + \frac{a_{\star}}{M}\alpha_{ij}\partial_{\xi}r_{\xi} = 0, \\ \left(r_{\xi}, (\alpha u)_{\xi}\right)\left(t = 0, \xi\right) = \begin{cases} (r_i, (\alpha \mathbf{u})_i \cdot \mathbf{n}_{ij}) & \text{if } \xi < 0, \\ \left(r_j, (\alpha \mathbf{u})_j \cdot \mathbf{n}_{ij}\right) & \text{otherwise.} \end{cases}$$

1. S. Dellacherie, P. Omnes, On the Godunov scheme applied to the variable cross-section linear equation. FVCA6, (4) :313–321, 2011.

Numerical scheme Cartesian mesh Triangular mesh

Numerical scheme

• Godunov scheme on a triangular or a cartesian mesh $(\Omega_i)_{1 \le i \le N}$ [DO11]

$$\begin{cases} \frac{d}{dt} (\alpha r)_i + \frac{a_{\star}}{2M} \frac{1}{|\Omega_i|} \sum_{\Gamma_{ij} \subset \partial \Omega_i} |\Gamma_{ij}| \Big[\big((\alpha \mathbf{u})_i + (\alpha \mathbf{u})_j \big) \cdot \mathbf{n}_{ij} + \alpha_{ij} (r_i - r_j) \Big] = 0, \\ \frac{d}{dt} (\alpha \mathbf{u})_i + \frac{a_{\star}}{2M} \frac{\alpha_i}{|\Omega_i|} \sum_{\Gamma_{ij} \subset \partial \Omega_i} |\Gamma_{ij}| \Big[r_i + r_j + \frac{\kappa}{\alpha_{ij}} \big((\alpha \mathbf{u})_i - (\alpha \mathbf{u})_j \big) \cdot \mathbf{n}_{ij} \Big] \mathbf{n}_{ij} = 0 \\ \text{with } \kappa = 1. \end{cases}$$

• We write it under the form

$$\frac{d}{dt}(\alpha q_h) + \frac{\mathbb{L}^h_{\kappa,\alpha}}{M}(q_h) = 0,$$

where $q_h = (r_i, \mathbf{u}_i)^T$.

Numerical scheme Cartesian mesh Triangular mesh

Tools and initial condition

Tools :

- *Mesh* : Software SALOME.
- Code : Library C++ CDMATH (in developing in CEA).

Initial condition :

• For all
$$(x, y) \in [0, 1[\times[0, 1[, 0 + 1[, 0 + 1]] + 1]) \in \mathcal{C}(\frac{1}{2}, \frac{1}{2}),$$

• $\alpha(x, y) = \begin{cases} \frac{1}{2} \text{ if } (x, y) \in \mathcal{C}(\frac{1}{2}, \frac{1}{2}), \\ 1 \text{ otherwise,} \end{cases},$
• $r^0(x, y) = 1,$
• $(\alpha \mathbf{u})^0 = \nabla \times \psi \text{ where } \psi(x, y) = \frac{2}{\pi} \left(\sin^2(\pi x) \sin^2(2\pi y) - \frac{1}{4} \right).$

We have

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$$\begin{cases} \nabla r^0 = 0\\ \nabla \cdot (\alpha \mathbf{u}^0) = \nabla \cdot (\nabla \times \psi) = 0 \end{cases} \Rightarrow q^0 = (r^0, \mathbf{u}^0)^T \in \mathcal{E}_{\alpha}.$$

Numerical scheme Cartesian mesh Triangular mesh

Cartesian mesh with $\kappa=1$:





• After 1000 iterations :

Numerical scheme Cartesian mesh Triangular mesh

• After 1000 iterations :

Cartesian mesh with $\kappa=0$:





Numerical scheme Cartesian mesh Triangular mesh

Triangular mesh with $\kappa = 1$:

• Initial condition :



Proposition ($\kappa = 1$ on \triangle)

$$\ker \mathbb{L}^h_{\kappa=1,\alpha} = \mathcal{E}^{h,\triangle}_{\alpha}$$

• After 1000 iterations :

Intermediate conclusion : The Godunov scheme

- preserves the incompressible states $q_h \in \mathcal{E}^{h, \triangle}_{\alpha}$ on triangular meshes,
- needs a correction $(\kappa = 0)$ to preserve the incompressibles states $q_h \in \mathcal{E}^{h,\square}_{\alpha}$ on **cartesian** meshes.

Godunov scheme and well-prepared states :

Definition

A state q^0 is said **well-prepared** if

$$||q^0 - \mathbb{P}_{\alpha}q^0||_{L^2_{\alpha}} = O(M),$$

where \mathbb{P}_{α} is the orthogonal projection on \mathcal{E}_{α} .

We want to find a correction $(\kappa =?)$ on **cartesian** meshes satisfying $\|q^0 - \mathbb{P}_{\alpha}q^0\|_{L^2_{\alpha}} = O(M) \Rightarrow \forall t \leq ?, \ \|q(t) - \mathbb{P}_{\alpha}q^0\|_{L^2_{\alpha}} = O(M)$

and that allows to recover the Godunov scheme when the Mach number goes to 1.

Definition Results Conclusion

Initial condition :

- $a_{\star} = 1$.
- $M = 10^{-4}$.
- $q^0 = q_1^0 + \mathbf{M} q_2^0$ with

$$\begin{cases} r_1^0(x,y) = 1, \\ (\alpha \mathbf{u}_1)^0 = \nabla \times \psi, \end{cases} \Rightarrow q_1^0 \in \mathcal{E}_\alpha \end{cases}$$

and

$$\left\{ \begin{aligned} r_2^0(x,y) &= 0, \\ \mathbf{u}_2^0 &= \nabla \phi, \\ \|q_2^0\|_{L^2_\alpha} &= 1, \end{aligned} \right. \Rightarrow q_2^0 \in \mathcal{E}_\alpha^\perp \label{eq:update}$$

then

$$||q^0 - \mathbb{P}_{\alpha}q^0||_{L^2_{\alpha}} = ||Mq^0_2||_{L^2_{\alpha}} = M = O(M).$$

• We will plot $||q - \mathbb{P}_{\alpha}q^{0}||_{L^{2}_{\alpha}}(t)$ as a function of the time.

Cartesian mesh with $\Delta x = \Delta y = 0.02, M = 10^{-4}$:



Théorème ($\kappa = 1$ on \Box)

$$\begin{aligned} \forall C_1 > 0, \ \exists C_2(C_1) > 0, \ \exists C_3(C_1) > 0, \ \|q^0 - \mathbb{P}^{h,\square}_{\alpha} q^0\|_{L^2_{\alpha}} &= C_1 M \\ \Rightarrow \forall t \ge C_2 M, \ \|q - \mathbb{P}^{h,\square}_{\alpha} q^0\|_{L^2_{\alpha}}(t) \ge C_3 \min(\Delta x, \Delta y), \end{aligned}$$

for all $M \leq \frac{C_3}{C_1} \min(\Delta x, \Delta y)$.

Cartesian mesh with $\Delta x = \Delta y = 0.02, M = 10^{-4}$:



Théorème ($\kappa = M$ on \Box)

$$\begin{aligned} \forall C_1, C_2 > 0, \ \exists C_3(C_1, C_2) > 0, \ \| q^0 - \mathbb{P}^{h, \square}_{\alpha} q^0 \|_{L^2_{\alpha}} &= C_1 M \\ \Rightarrow \forall t \in [0; C_2 M], \ \| q - \mathbb{P}^{h, \square}_{\alpha} q^0 \|_{L^2_{\alpha}}(t) \le C_3 M, \end{aligned}$$

where C_3 does not depend on M.

Cartesian mesh with $\Delta x = \Delta y = 0.02, M = 10^{-4}$:



Théorème ($\kappa = 1$ on \triangle and $\kappa = 0$ on \Box)

$$\begin{aligned} \forall C_1, C_2 > 0, \ \exists C_3(C_1, C_2) > 0, \ \|q^0 - \mathbb{P}^{h, \bigtriangleup \ or \ \Box}_{\alpha} q^0\|_{L^2_{\alpha}} &= C_1 M \\ \Rightarrow \forall t \ge 0, \ \|q - \mathbb{P}^{h, \bigtriangleup \ or \ \Box}_{\alpha} q^0\|_{L^2_{\alpha}}(t) \le C_3 M, \end{aligned}$$

where C_3 does not depend on M.

 $\begin{array}{c} {\rm Definition} \\ {\rm Results} \\ {\rm Conclusion} \end{array}$

Conclusions et perspectives

 $\underline{\text{Conclusions}}$:

- $\bullet\,$ We explain the influence of cell geometry at low Mach :
 - good behavior of the Godunov scheme ($\kappa = 1$) on triangular meshes (ker $\mathbb{L}_{\kappa=1,\alpha}^{h,\Delta} = \mathcal{E}_{\alpha}^{h,\Delta}$).
 - bad behavior of the Godunov scheme ($\kappa = 1$) on **cartesian** meshes (ker $\mathbb{L}_{\kappa=1,\alpha}^{h,\Box} \subsetneq \mathcal{E}_{\alpha}^{h,\Box}$).
- We propose two corrections at low Mach number on **cartesian** meshes :
 - $\kappa = 0$: good correction but it is not continuous against the Mach number.
 - $\kappa = M$: good correction continuous against the Mach number.

Perspectives :

- Test the method in the non-linear case.
- Prove similar properties for the non-linear case.

Thank you for your attention!



Definition Results Conclusion

S. Dellacherie, P. Omnes. On the Godunov scheme applied to the variable cross-section linear equation. FVCA6, (4) :313–321, 2011.